Structured Meta-Learning for **Cross-Domain Few-Shot Classification**

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Few-Shot Learning (FSL)



Many-Shot





Few-Shot

- A task is a problem that a machine learning model solves by adapting to some data
- In FSL, few training samples from the task are available
- Incredibly difficult for data-hungry models
- Humans can easily deal with the problem thanks to **experience**

From "Learning" to "Learning to Learn"

Training



Kitten

Puppy



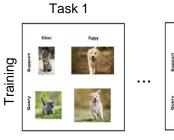






Dataset

- A single task
- Objective: generalize to new examples within a task





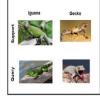
Task

Task 1

Test







Meta-Dataset (our experience!)

- Many FSL tasks
- Objective: generalize to new tasks

Meta-Learning



- The goal of Meta-Learning is "learning to learn"
 - Extracts and reuses knowledge by training on a **distribution of tasks** p(T)
- Characterized by the presence of a learner and a meta-learner
 - The learner follows an adaptation procedure to adapt to the task at hand
 - The meta-learner adjusts the adaptation procedure to improve performance over many tasks

MAML

Require: p(T): distribution over tasks **Require:** α, β : step size hyperparameters

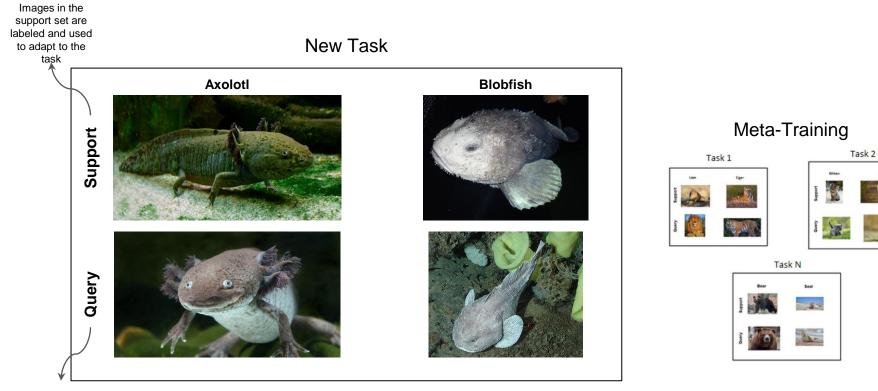
- 1: randomly initialize θ
- 2: while not done do
- 3: Sample batch of tasks $\mathcal{T}_i \sim p(\mathcal{T})$
- 4: for all \mathcal{T}_i do
- 5: Evaluate $\nabla_{\theta} \mathcal{L}_{\mathcal{T}_i}(f_{\theta})$ with respect to K examples
- 6: Compute adapted parameters with gradient descent: $\theta'_i = \theta \alpha \nabla_{\theta} \mathcal{L}_{\mathcal{T}_i}(f_{\theta})$

7: end for

- 8: Update $\theta \leftarrow \theta \beta \nabla_{\theta} \sum_{\mathcal{T}_i \sim p(\mathcal{T})} \mathcal{L}_{\mathcal{T}_i}(f_{\theta'_i})$
- 9: end while

- Applies to a generic learner with parameters θ
- Only requirement for the learner is to be trainable via gradient descent
- Finds a single parameter initialization for the learner
- The algorithm features a nested loop
 - Inner loop: the learner
 - Outer loop: the meta-learner

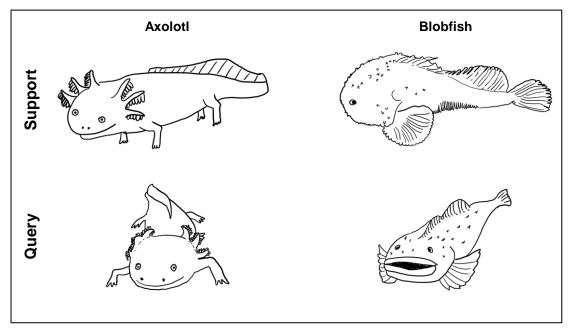
One-Shot Classification



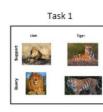
Images in the query set are unlabeled and the learner predicts their label

One-Shot Classification

New Task: Sketch



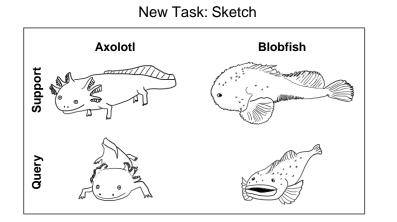
Meta-Training: Natural

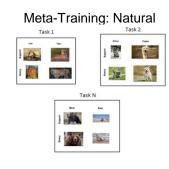


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Cross-Domain Few-Shot Learning (CDFSL)





- The above is an example of CDFSL, easy for humans and hard for meta-learning
- CDFSL deals with data coming from *heterogeneous domains*
 - Examples: different source cameras or different light conditions
- In our case:
 - the domain does not change same within a task
 - test tasks feature data from unseen domains
- We want to refine meta-learning techniques to deal with CDFSL

Disentangled and Simple Embedding



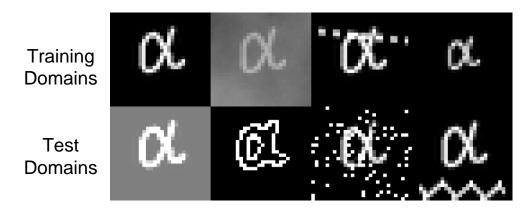
"[W]e would like our representations to disentangle the factors of variation" Bengio et al. 2013

- Disentanglement captures different independent properties of data in different units
- Many works argue that a disentangled embedding could prove useful in general
- Others believe training a **simple embedding** with few regularizations is enough
- We believe disentanglement to be the better solution for CDFSL:
 - Previous works have leveraged disentanglement to boost performance in standard FSL
 - Capturing domain information may be useful

[Bengio et al. 2013, Van Steenkiste et al. 2019, Chen et al. 2019]

Our Contribution

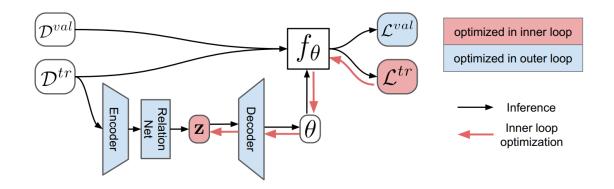
Benchmark: Corrupted-Omniglot



- We obtain *Corrupted-Omniglot* by augmenting the dataset of characters *Omniglot* with image corruptions
- Each corruption is a domain
- 16 domains are split into *training* and *test domains*
- 20-way, 1-shot tasks (20 classes per task, 1 example per class)

[Lake et al. 2019, Mu et al. 2019]

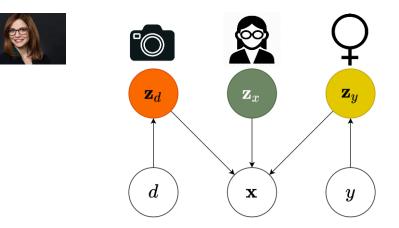
Meta-Learning Model: LEO



- Features inner task-specific loop and outer across-task loop, like MAML
- Encodes the task into a latent code
- Decodes the parameters of the learner from the latent code
- Performs gradient descent in the latent code

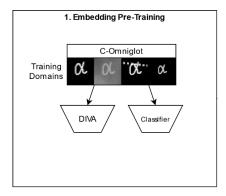
[Rusu et al. 2019]

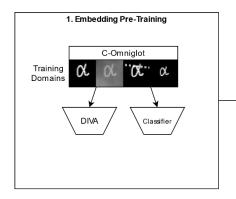
Disentanglement Model: DIVA

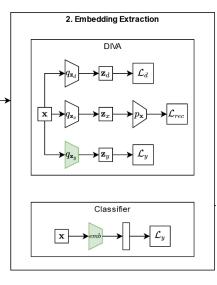


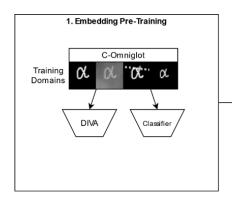
- Encodes the input in a disentangled representation
- The latent space is divided in three subspaces
 - Domain, residual, and class information
- Latent space in continuous and stochastic
 - Can potentially generalize to unseen domains

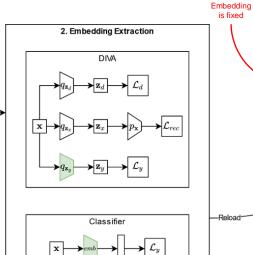
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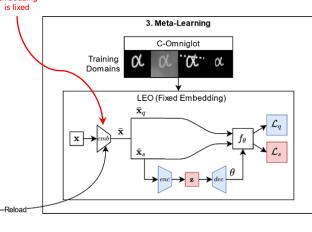


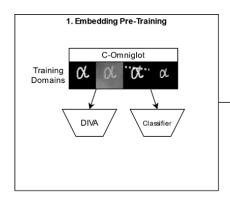


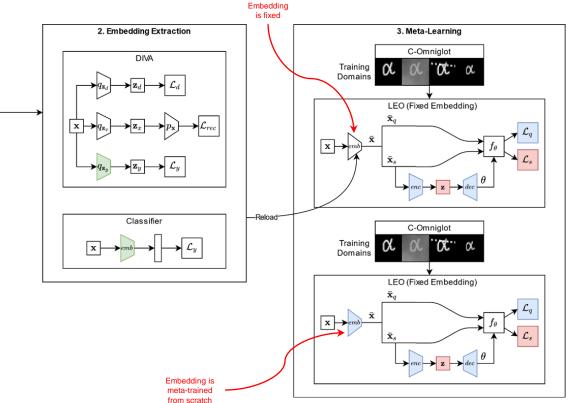












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Very general character shows up when not considering z_y during reconstruction

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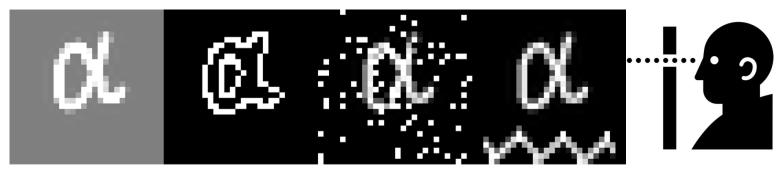
Meta-Learning Results

	Class Accuracy					
Embedding	Training Domains	Test Domains				
DIVA	0.91	0.72				
Classifier	0.88	0.64				
Meta-Trained	0.95	0.76				

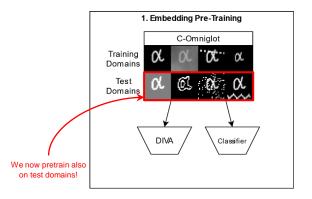
- DIVA is much better than Classifier in test domains
 - Promising!
- Meta-trained embedding outperforms both pre-trained embeddings
 - Not so promising...
 - Meta-training may play an important role in generalizing to unseen domains

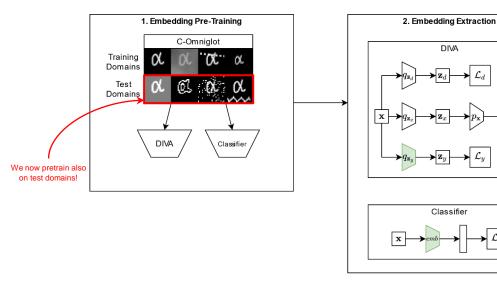
Introducing Oracle Models

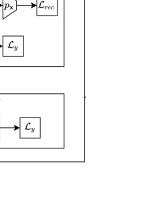
Test Domains

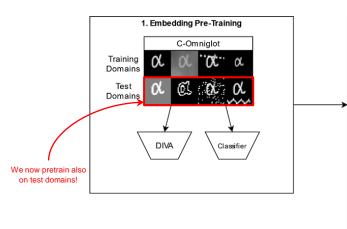


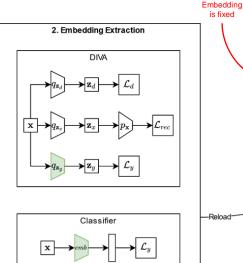
- What if we had a disentangling model that can generalize to unseen domains?
- We can position ourselves in this "what if" scenario by leveraging oracle models
 - Oracle models are trained on images from **both training and test domains**

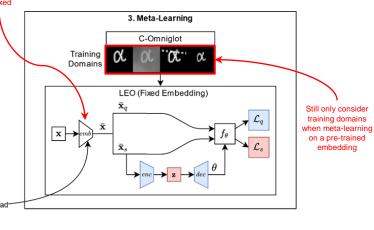


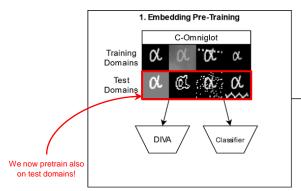


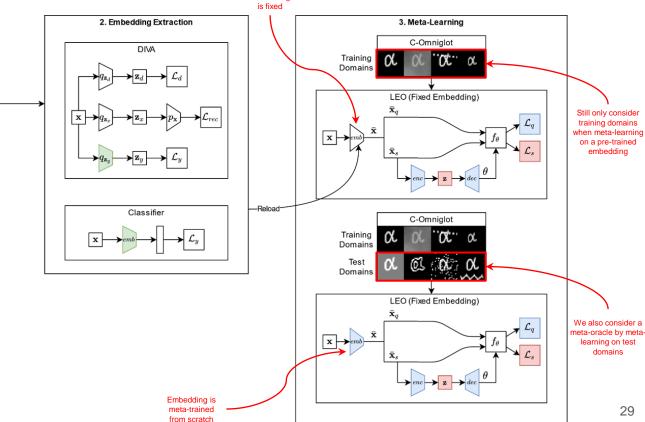












Embedding



Very general character shows up when not considering z_y during reconstruction

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Meta-Learning Oracle Results

	Class Accuracy			
Embedding	Training Domains	Test Domains		
Oracle DIVA	0.91	0.87		
Oracle Classifier	0.94	0.90		
Meta-Oracle	0.94	0.93		

- Oracle Classifier outperforms Oracle DIVA!
 - Maybe disentanglement is not useful in our problem after all...
- Meta-Oracle is the best one, by far
 - Yet again hinting at importance of meta-training

Leveraging Oracle Domain Information

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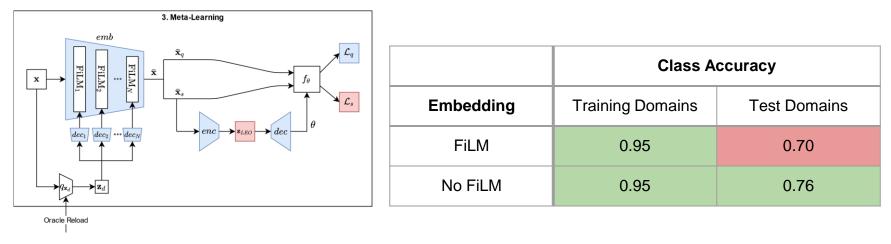
- We are not yet done with disentanglement
- Oracle DIVA provides us with high-quality domain information
- Is there any use for domain information in our problem?

Including Oracle Domain in the Embedding

2. Embedding Extraction			
$ \qquad \qquad$		Class A	ccuracy
$\mathbf{x} \rightarrow q_{\mathbf{z}_x} \rightarrow \mathbf{z}_x \rightarrow p_{\mathbf{x}} \rightarrow \mathcal{L}_{rec}$	Embedding	Training Domains	Test Domains
	Oracle DIVA zd+zy	0.90	0.64
$ \qquad \qquad$	Oracle DIVA zy 0.88	0.88	0.85

- We consider both class and domain information when reloading Oracle DIVA's embedding
 - LEO may improve the quality of adaptation based on domain information
- The model overfits on training domains

Oracle Domain-Based Modulations



- We leverage modulations between the layers of the embedder
 - The parameters of the modulation are inferred based on domain information
 - Modulations may help in filtering domain information in the embedding, boosting performance
- Again, overfitting on training domains

[llse et al. 2018]

Takeaways

- Main takeaway: disentanglement does not seem to do much
 - Domain information is hard to leverage
- Many works in the literature claim disentanglement is useful...
 - ...not enough experiments?
 - ...biased literature?
- Other observations:
 - Meta-training a simple embedding is beneficial as opposed to pre-training
 - Filtering domain information boosts performance



VS



Future Work

- Verify our results on disentanglement with **further experimentation**
- If our results are verified:
 - Another interesting direction is to pursue *domain agnostic* representations
 - The adaptation process can be refined to learn how to filter unseen domain information from few samples





Any questions?