

PC-GAU: PCA basis of Scattered Gaussians for Shape Matching via Functional Maps

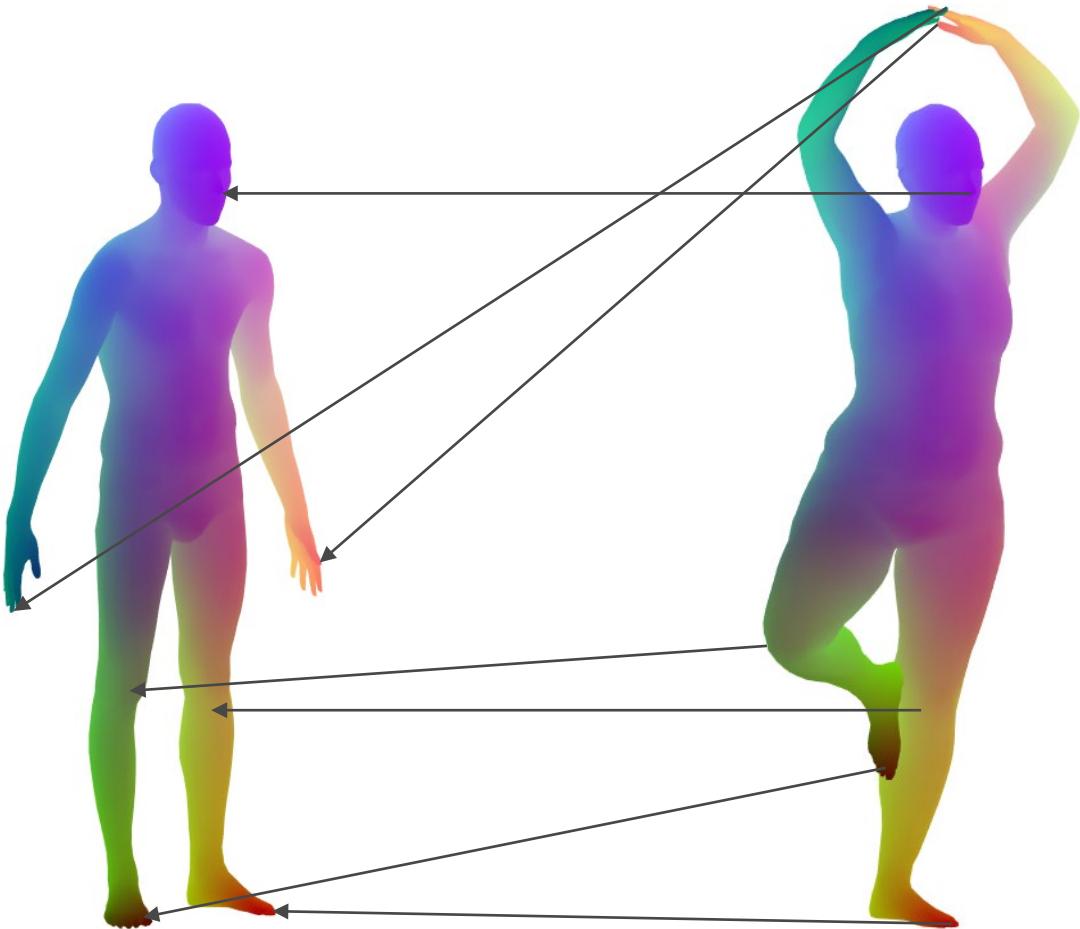
Michele Colombo
michele11.colombo@mail.polimi.it
CSE Track



POLITECNICO
MILANO 1863



Shape Matching: intuitive idea



Find
correspondences
between the
points of two 3D
shapes

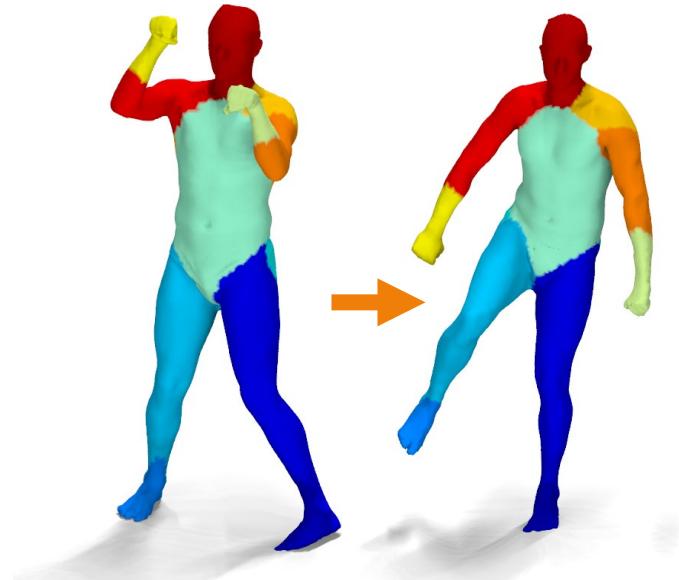
Shape Matching: applications

Transfer of **information** between shapes

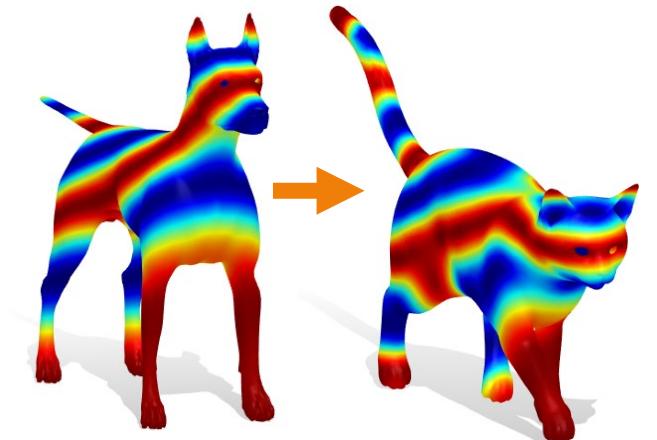
- Texture Transfer
- Segmentation transfer
- Function transfer
(e.g. deformation)



Source: Melzi et al, ACM TOG 2019



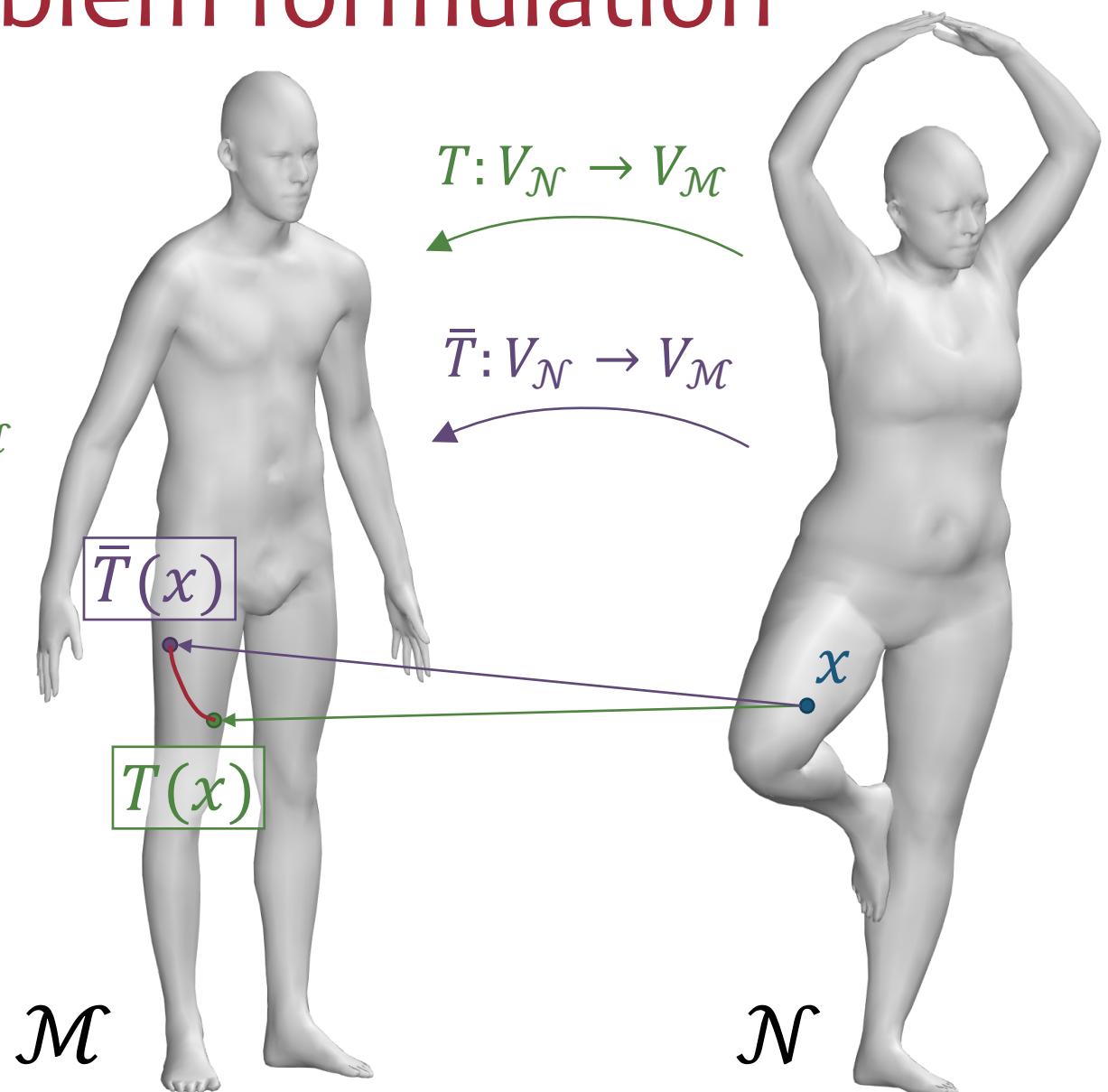
Source: Ovsjanikov et al, ACM TOG 2012



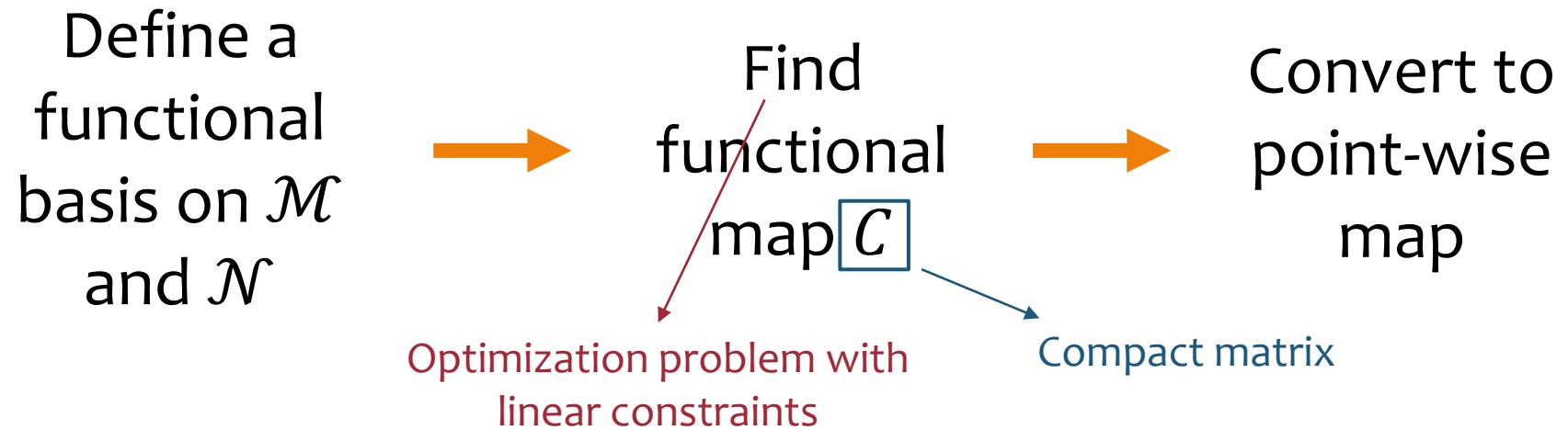
Source: Melzi et al, ACM TOG 2019

Shape Matching: problem formulation

- **Input:** pair of meshes \mathcal{M} and \mathcal{N} ,
vertices $V_{\mathcal{M}}$ and $V_{\mathcal{N}}$
- Unknown correspondence $T: V_{\mathcal{N}} \rightarrow V_{\mathcal{M}}$
- **Output:** point-wise map $\bar{T}: V_{\mathcal{N}} \rightarrow V_{\mathcal{M}}$
- **Goal:** \bar{T} similar to T
- Error evaluation:
$$e(x) = \text{geoDist}_{\mathcal{M}}(\bar{T}(x), T(x))$$

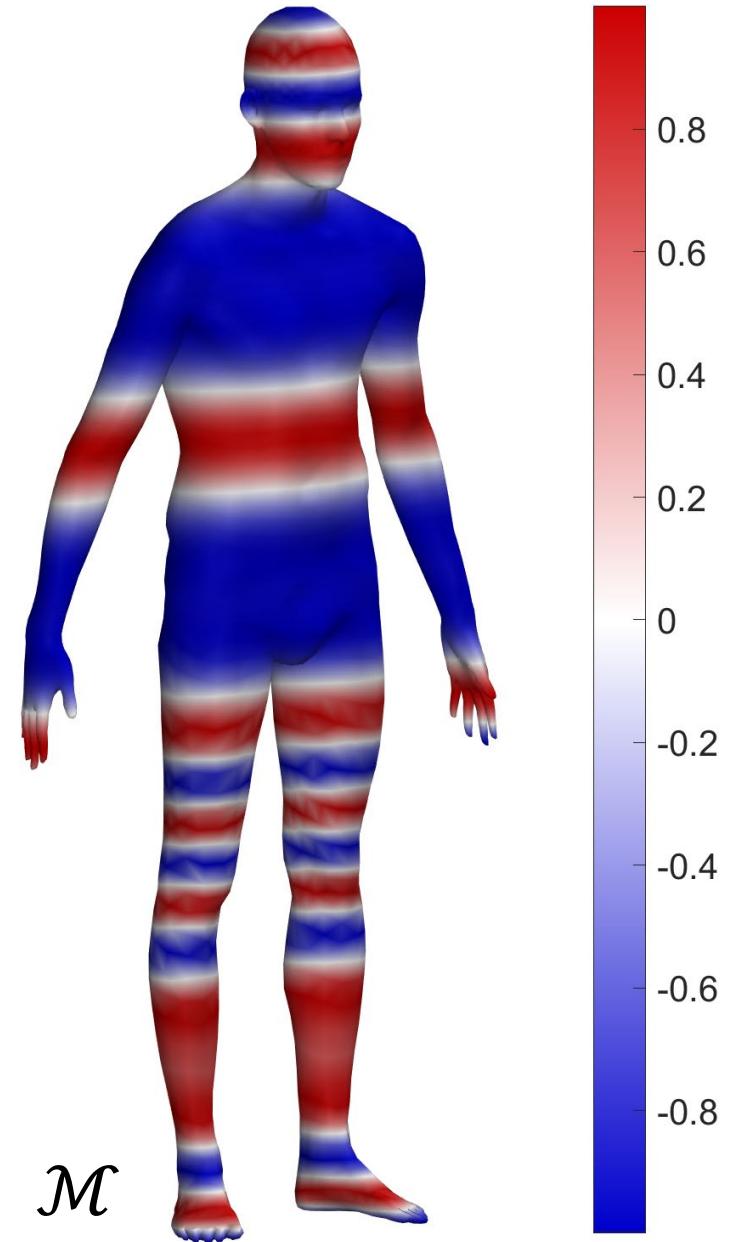


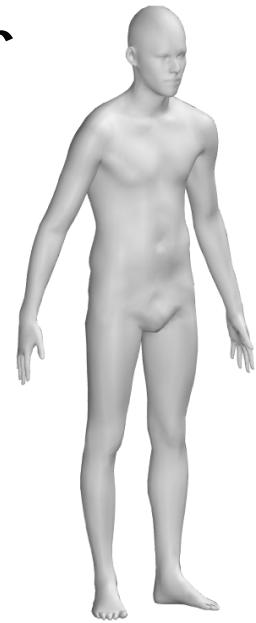
Shape Matching via Functional Maps [OBCS*12]



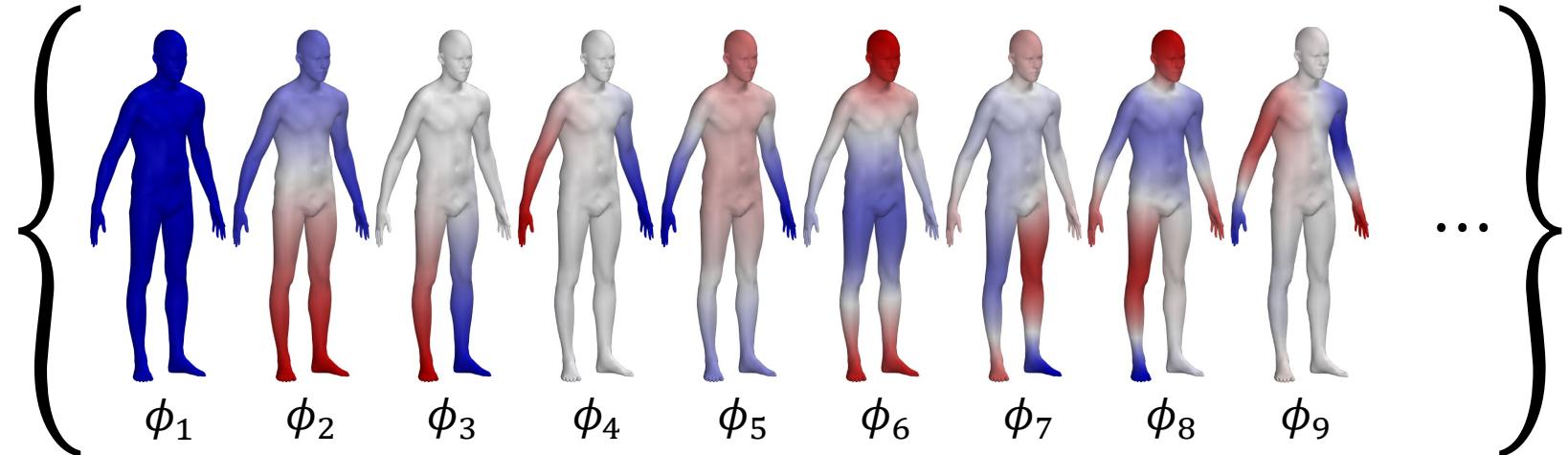
Functions defined on a mesh

- $f: V_{\mathcal{M}} \rightarrow \mathbb{R}$
- f vector $\in \mathbb{R}^n$, with $n = |V_{\mathcal{M}}|$
- $\mathcal{F}(\mathcal{M}, \mathbb{R})$ functional space of \mathcal{M}

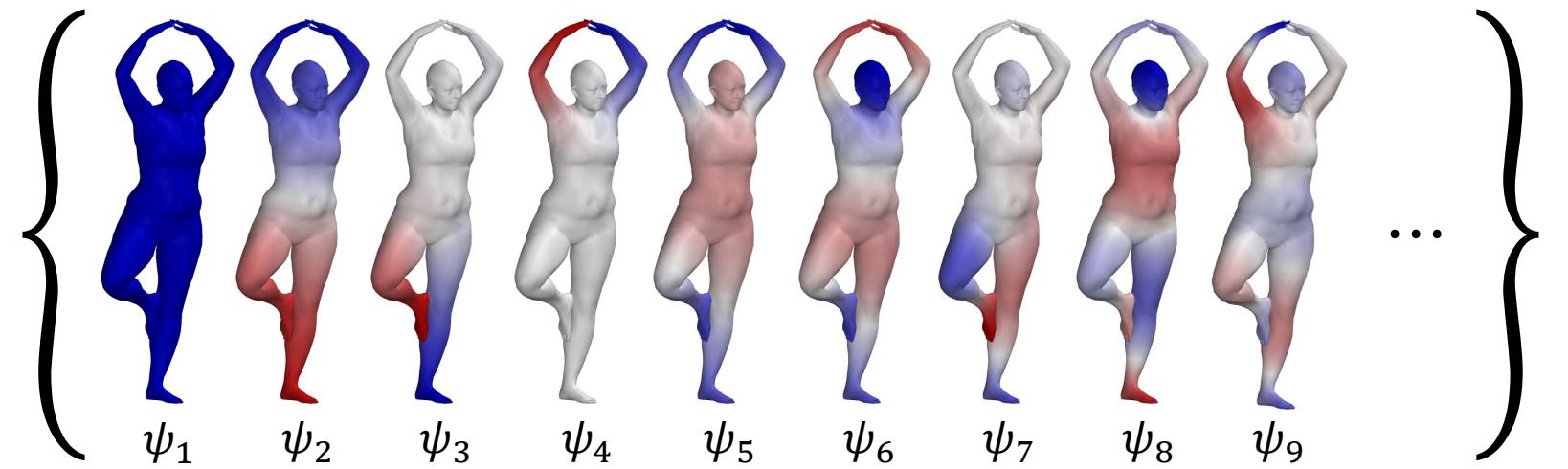


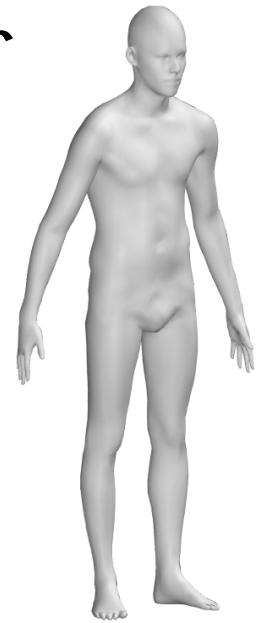
\mathcal{M} 

Functional basis

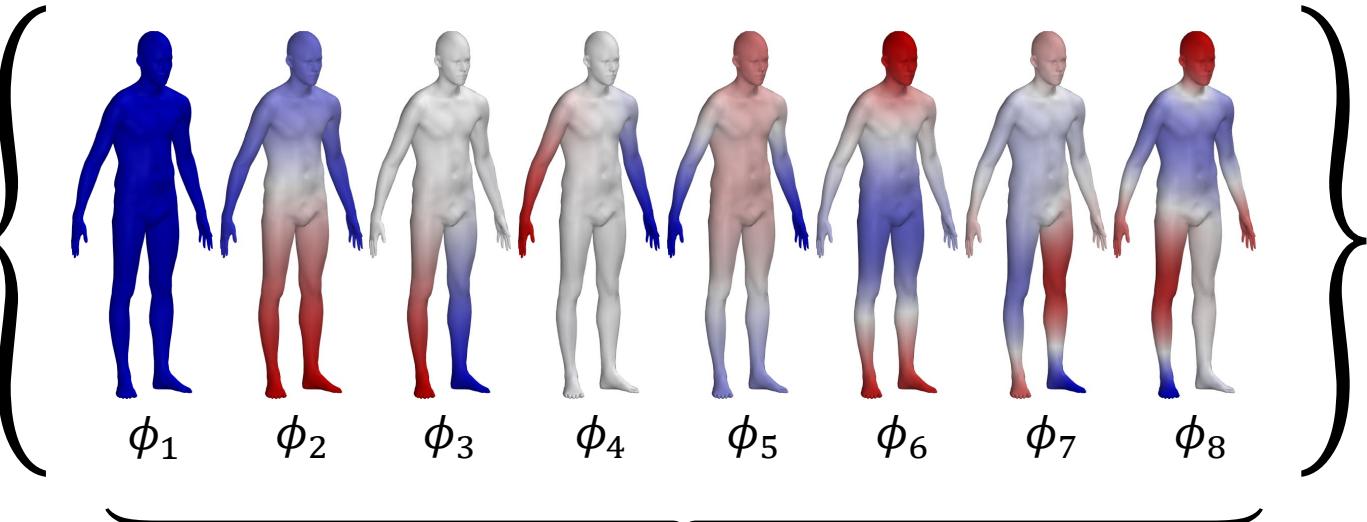
 $\Phi =$  \mathcal{N} 

Functional basis

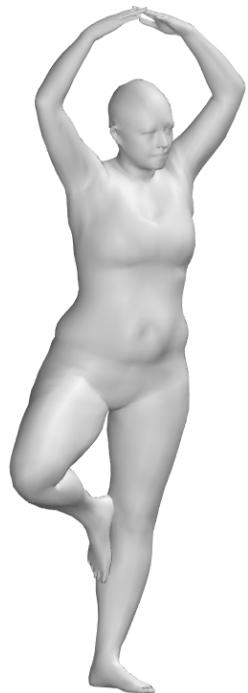
 $\Psi =$ 

\mathcal{M} 

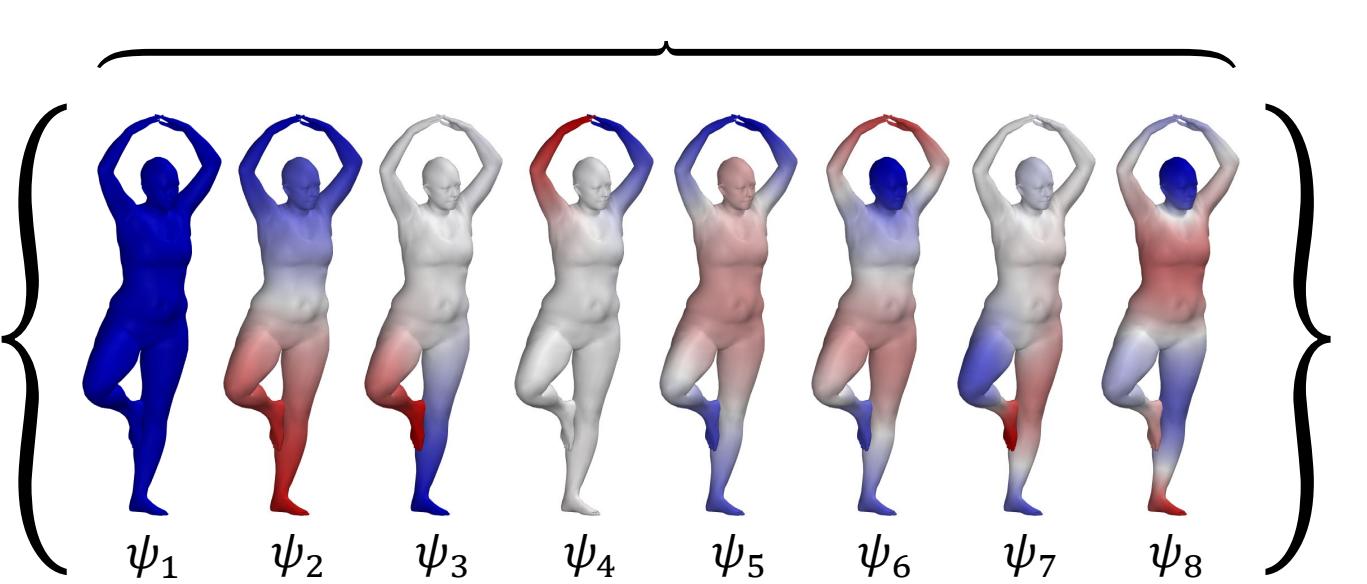
(truncated)
Functional
basis

 $\Phi =$ 

Matrices in $\mathbb{R}^{n \times k}$
(atoms as columns)

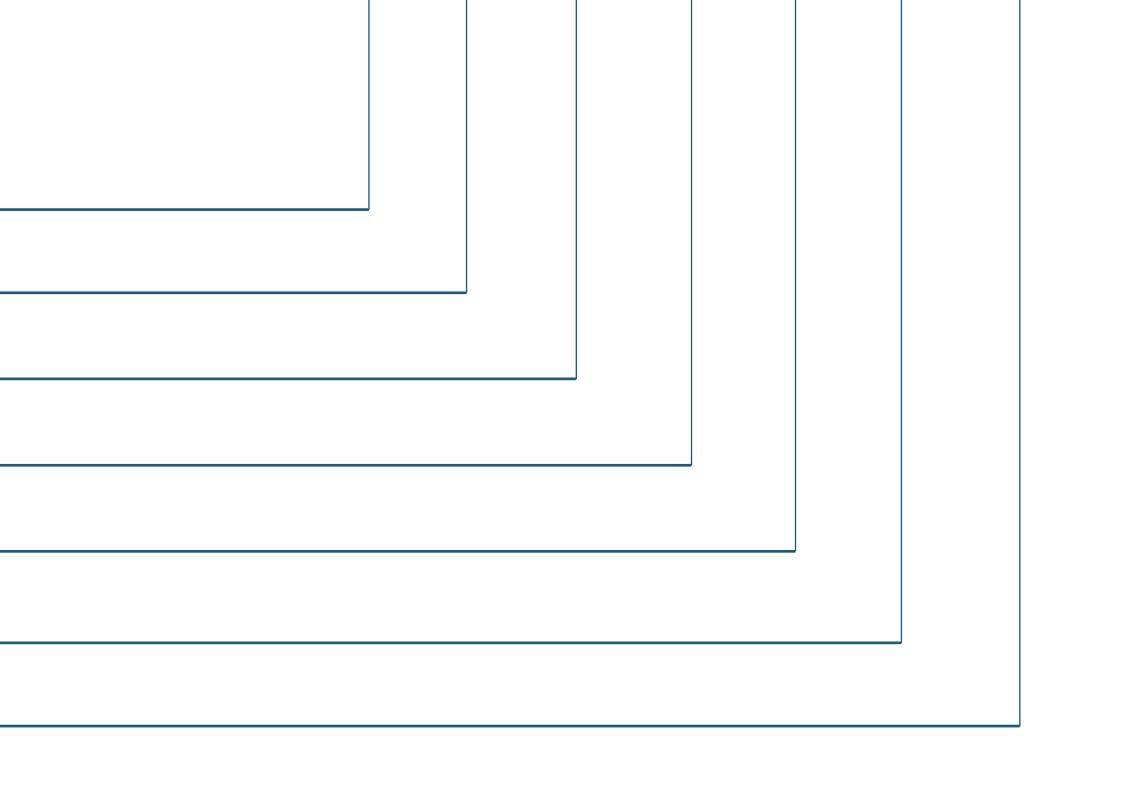
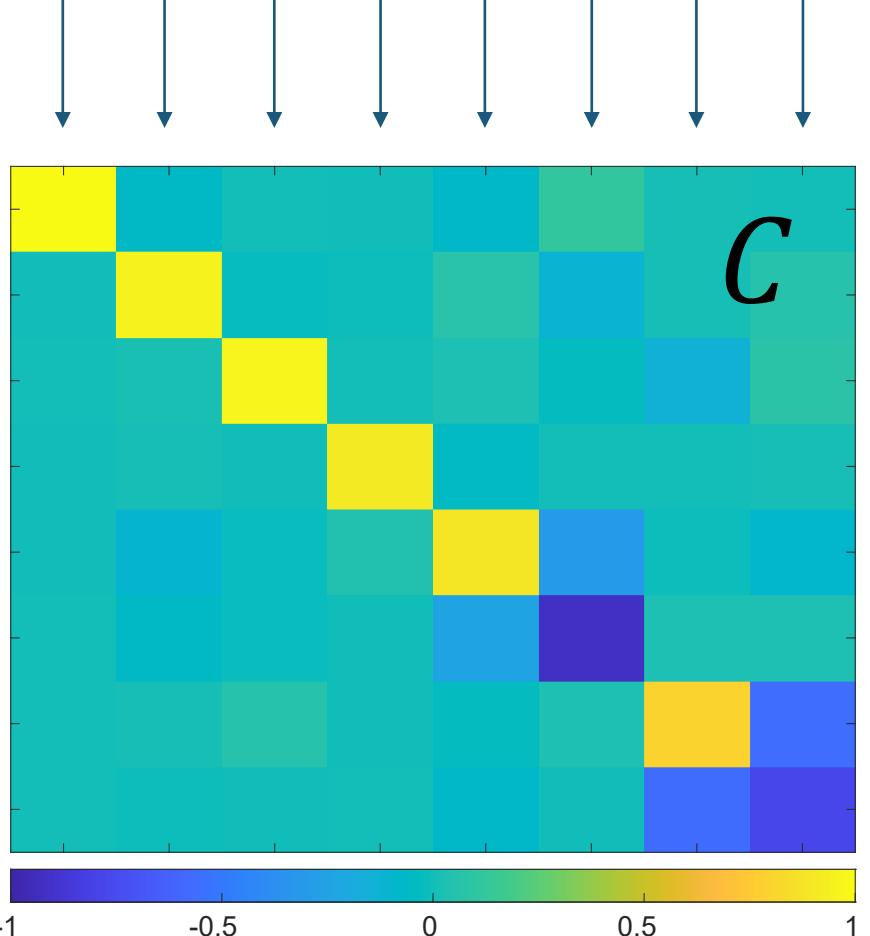
 $k = 8$ \mathcal{N} 

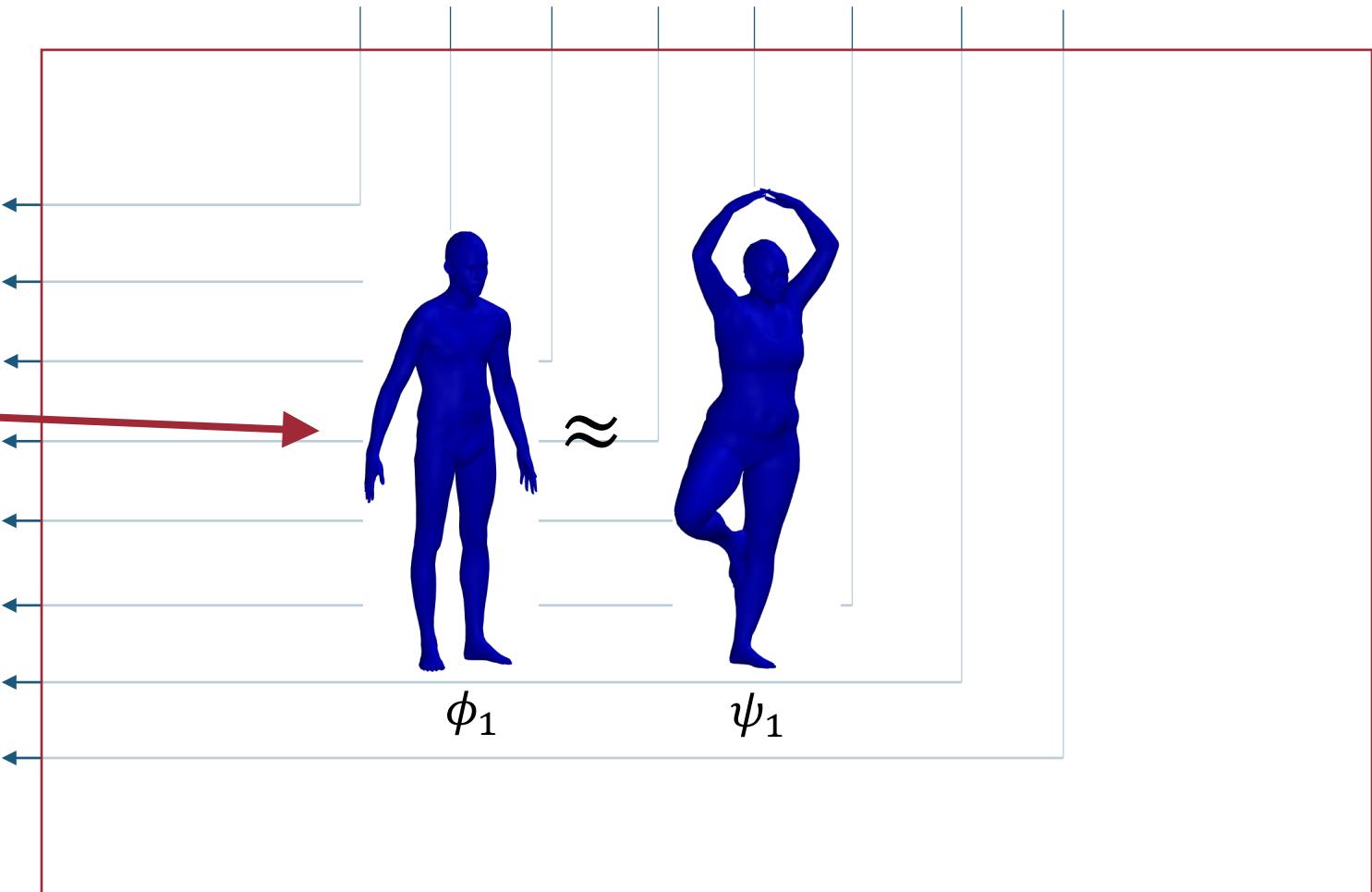
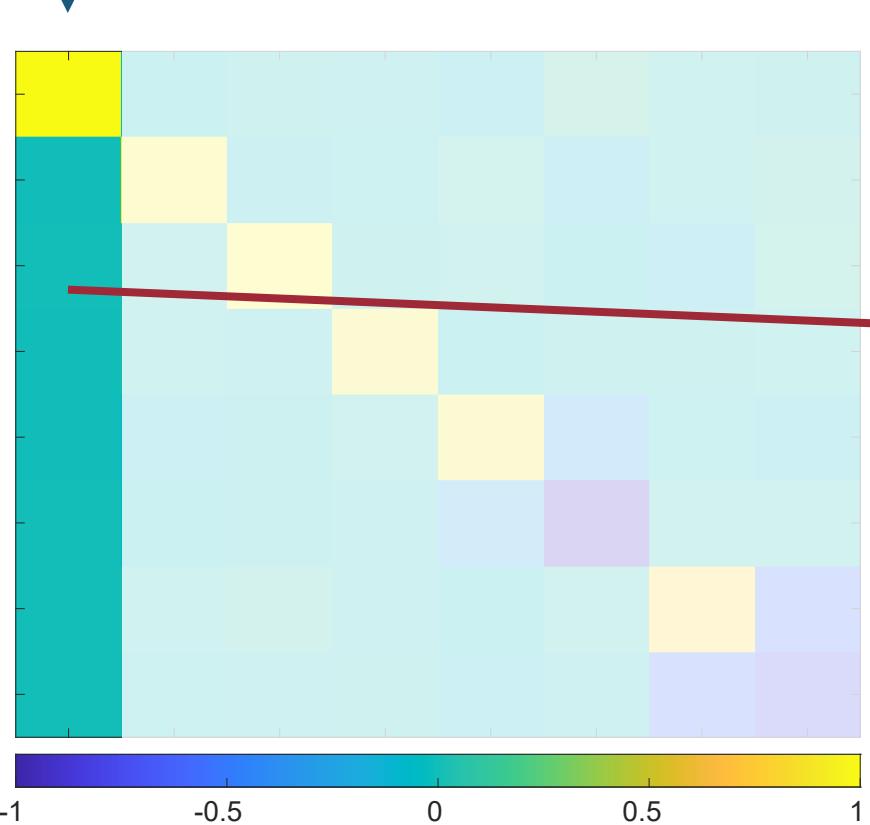
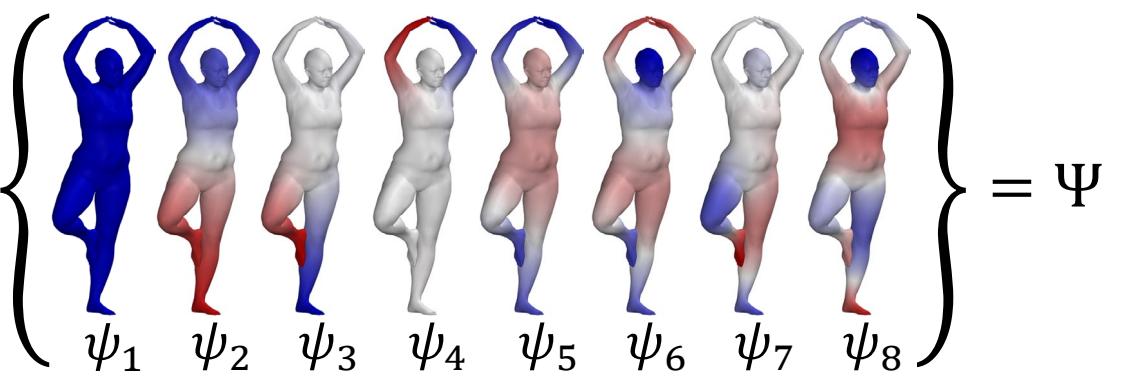
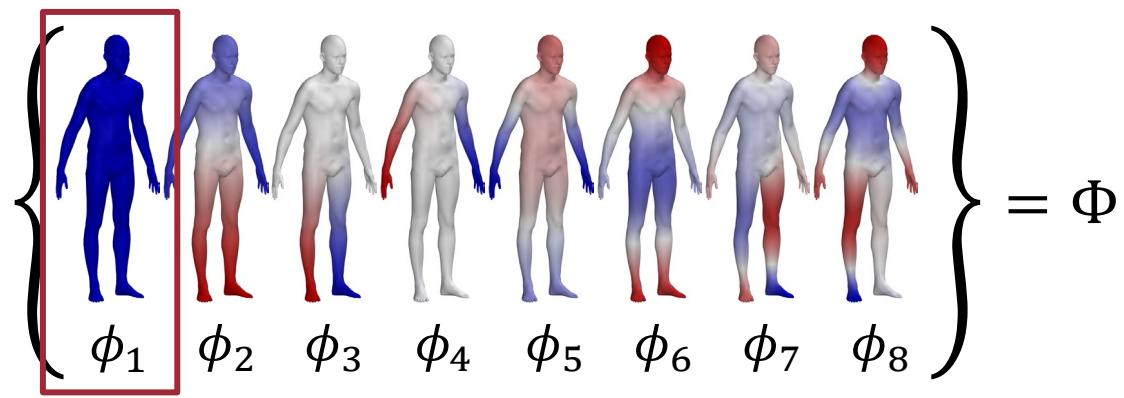
(truncated)
Functional
basis

 $\Psi =$ 

$$\left\{ \begin{array}{c} \text{Human 3D models} \\ \phi_1 \quad \phi_2 \quad \phi_3 \quad \phi_4 \quad \phi_5 \quad \phi_6 \quad \phi_7 \quad \phi_8 \end{array} \right\} = \Phi$$

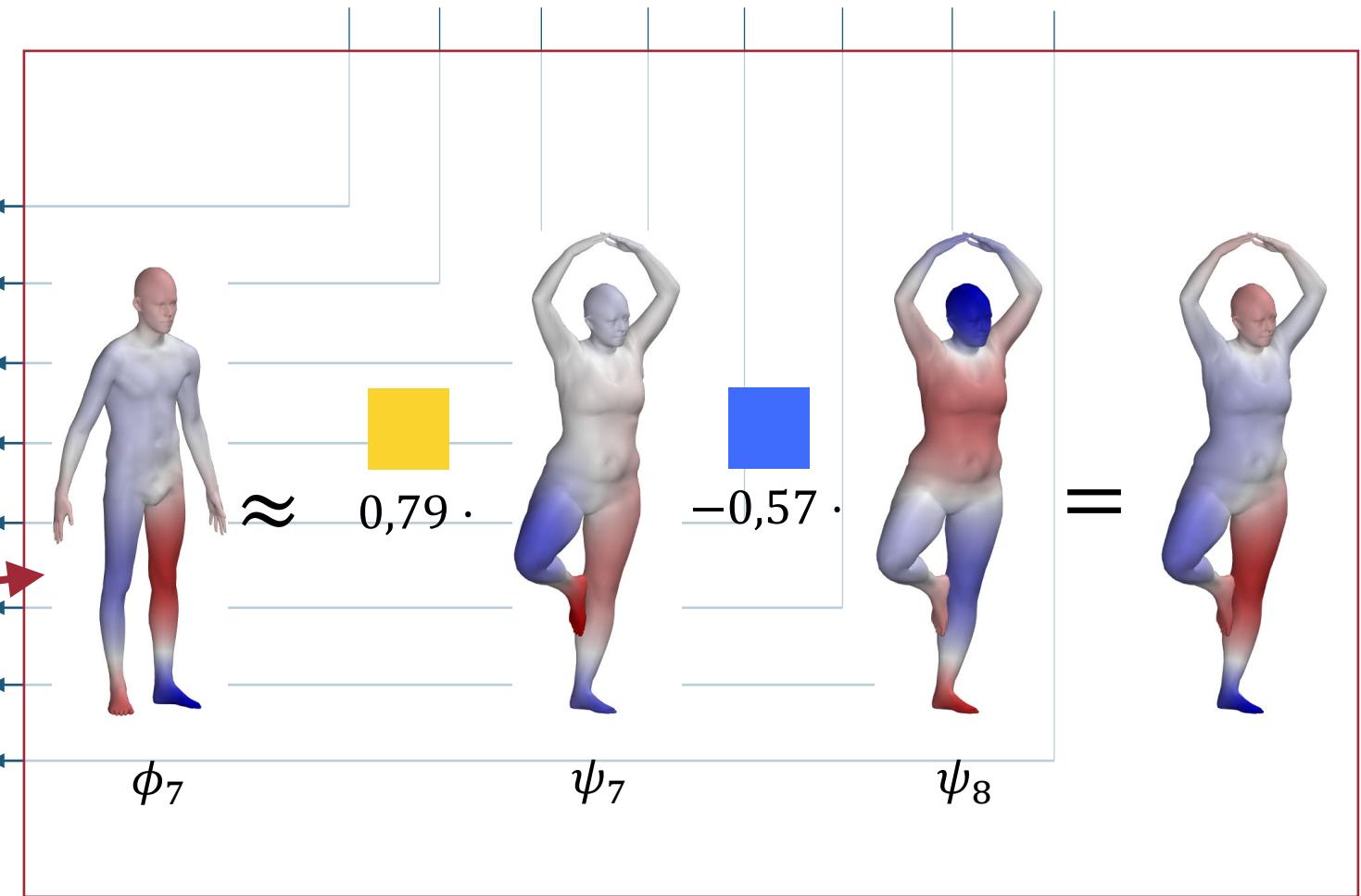
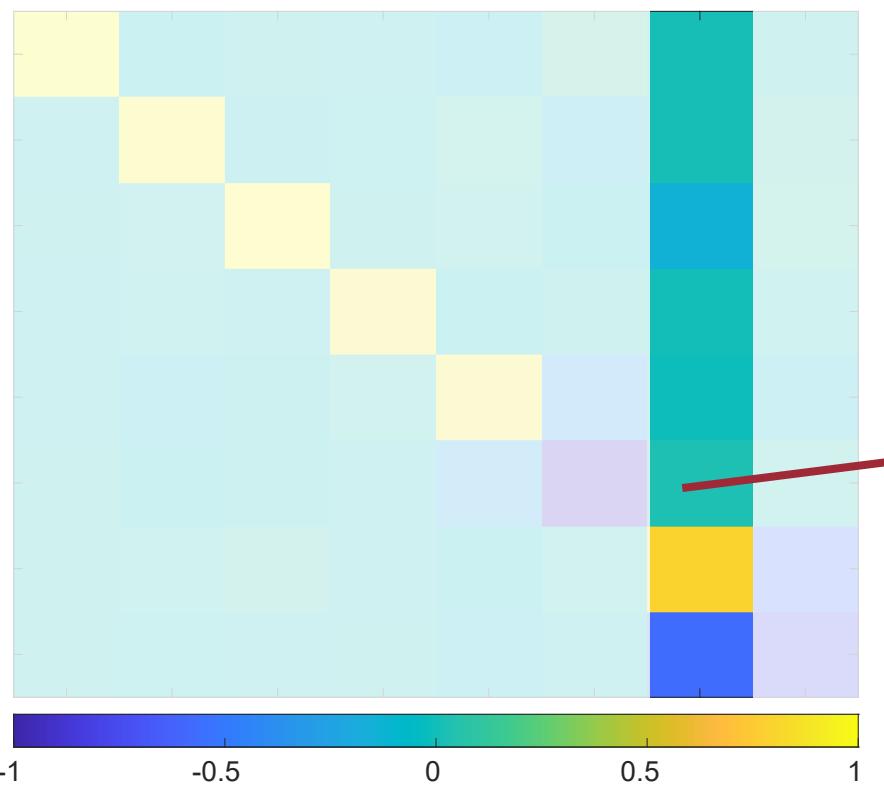
$$\left\{ \begin{array}{c} \text{Human 3D models} \\ \psi_1 \quad \psi_2 \quad \psi_3 \quad \psi_4 \quad \psi_5 \quad \psi_6 \quad \psi_7 \quad \psi_8 \end{array} \right\} = \Psi$$





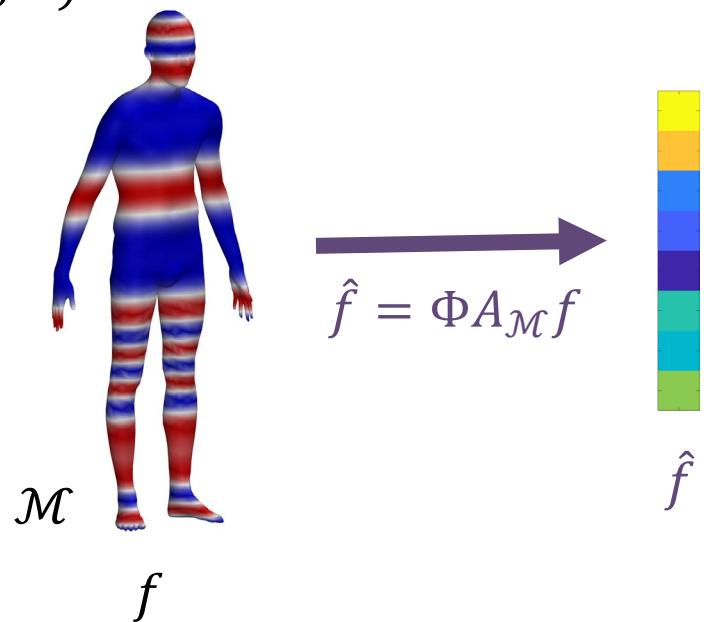
$$\left\{ \begin{array}{ccccccc} \text{Human 1} & \text{Human 2} & \text{Human 3} & \text{Human 4} & \text{Human 5} & \text{Human 6} & \text{Human 7} \\ \phi_1 & \phi_2 & \phi_3 & \phi_4 & \phi_5 & \phi_6 & \phi_7 \\ \end{array} \right\} = \Phi$$

$$\left\{ \begin{array}{ccccccc} \text{Human 1} & \text{Human 2} & \text{Human 3} & \text{Human 4} & \text{Human 5} & \text{Human 6} & \text{Human 7} \\ \psi_1 & \psi_2 & \psi_3 & \psi_4 & \psi_5 & \psi_6 & \psi_7 \\ \end{array} \right\} = \Psi$$

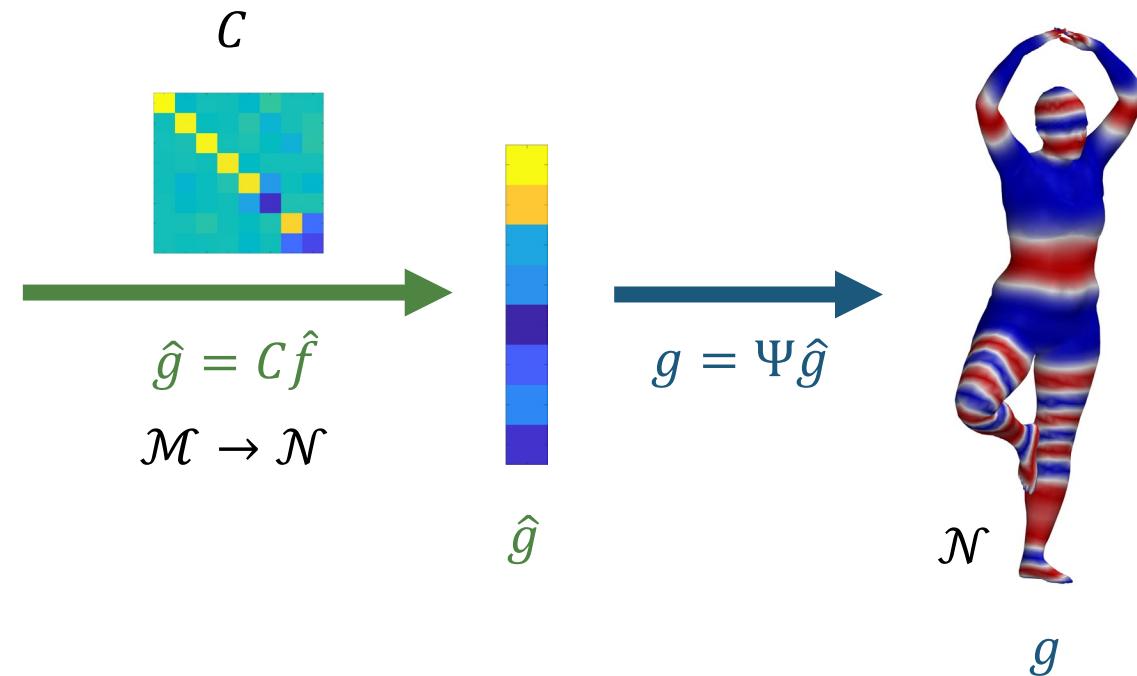


Function transfer through C

- \mathcal{M} with (truncated) orthonormal basis Φ
- \mathcal{N} with (truncated) orthonormal basis Ψ
- $C \in \mathbb{R}^{k \times k}$
- $f \in \mathcal{F}(\mathcal{M}, \mathbb{R})$



$$g = \underbrace{\Psi C \Phi A_{\mathcal{M}} f}_{\hat{f}} \longrightarrow \text{Coefficients of } f \text{ on } \Phi$$
$$\underbrace{\hat{g} = C \hat{f}}_{\hat{g}} \longrightarrow \text{Coefficients transferred on } \mathcal{N}$$
$$\underbrace{g = \Psi \hat{g}}_{g} \longrightarrow \text{Reconstruction of } g \text{ from coefficients } \hat{g}$$



Finding C

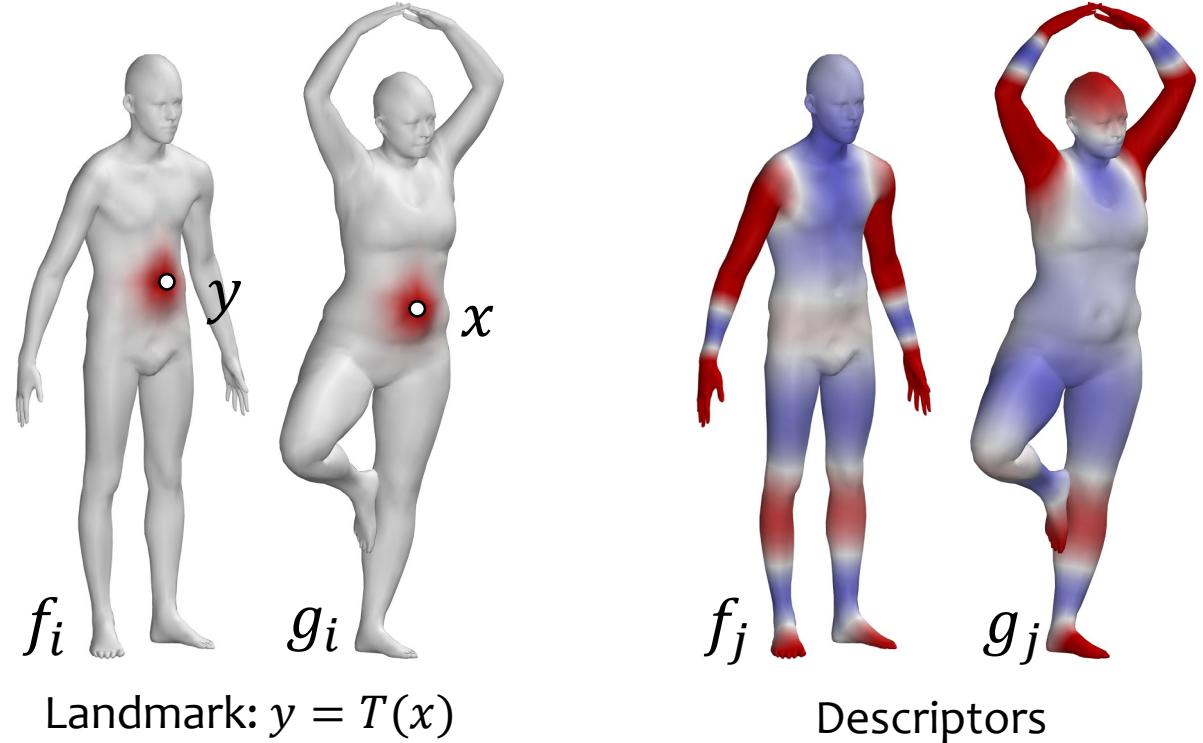
For each pair of corresponding functions f_i and g_i



Projection on Φ and Ψ

$$\hat{f}_i = \Phi A_{\mathcal{M}} f_i$$

$$\hat{g}_i = \Psi A_{\mathcal{N}} g_i$$



Preservation -> Constraint on C

$$\hat{g}_i = C \hat{f}_i$$

Optimization problem on C



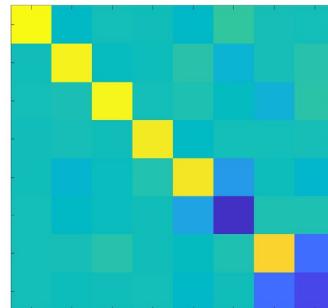
$$\min \sum_i \|\hat{g}_i - C \hat{f}_i\|_2^2$$

Linear in C

Converting C into a point-wise map [OBCS*12]

Given:

- \mathcal{M} with basis Φ
- \mathcal{N} with basis Ψ
- C from \mathcal{M} to \mathcal{N}



\mathcal{M}



$$\bar{T}: V_{\mathcal{N}} \rightarrow V_{\mathcal{M}}$$



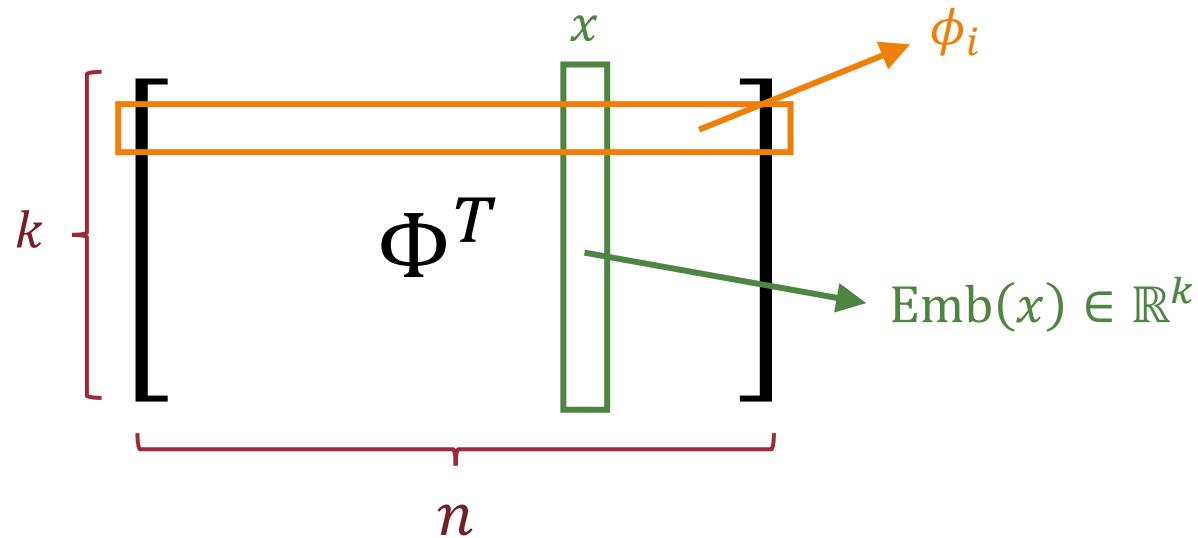
\mathcal{N}



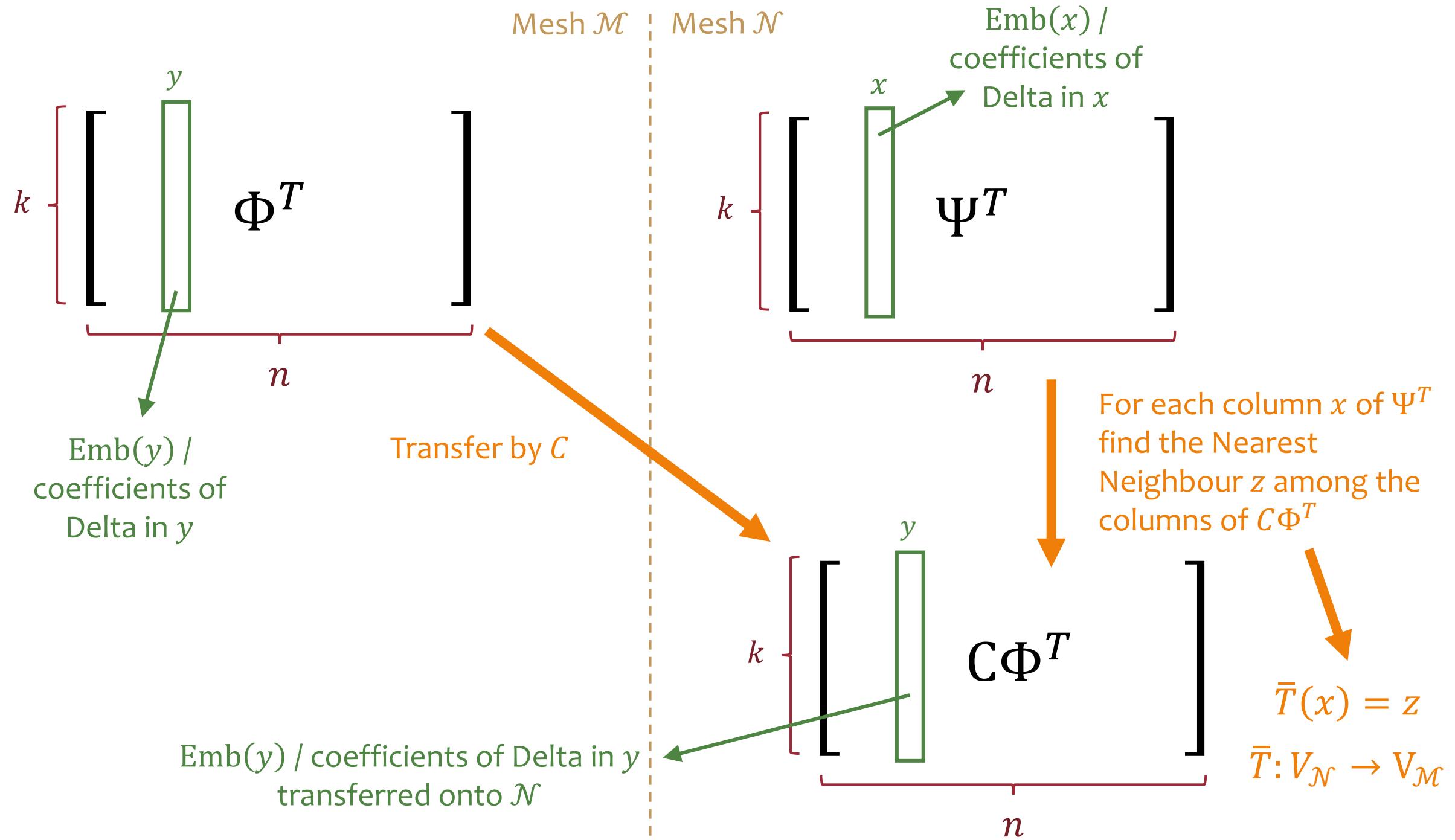
Embedding

- Mesh \mathcal{M} , basis $\Phi = \{\phi_i\}$, vertex $x \in V_{\mathcal{M}}$
- Embedding of x :

$$\text{Emb}(x) = [\phi_i(x)]$$



- k -dimensional representation of vertex x
- $\text{Emb}(x)$ are the coefficients in Φ of a Delta function centered in x



Locality preservation

- This method works if:

$$\|\text{Emb}(x) - \text{Emb}(y)\|_2 \approx \text{geoDist}(x,y) \quad \forall x, y \in \mathcal{M}$$

- In particular, **ordering** of $\|\text{Emb}(x) - \text{Emb}(y)\|$ and $\text{geoDist}(x,y)$ for all vertices y in a neighborhood of x should be preserved

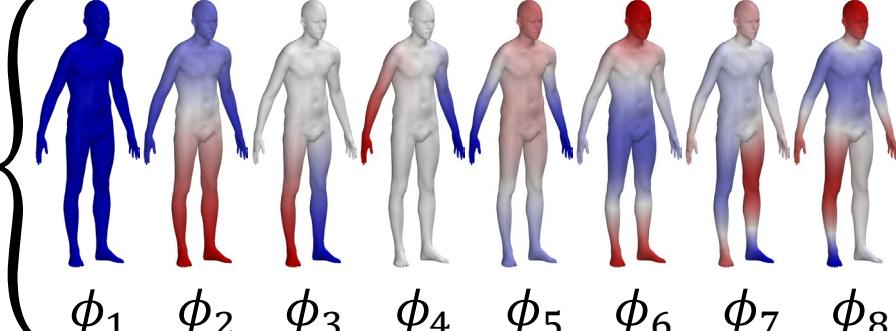


We will define a metric
for this property

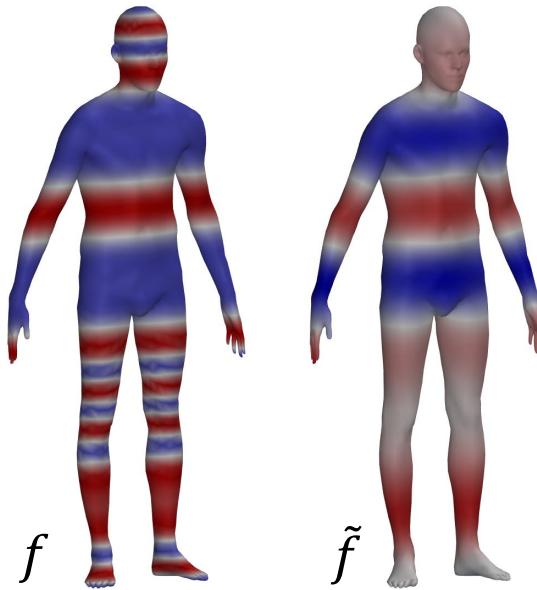
Φ should be **locality preserving** in $x, \forall x \in \mathcal{M}$

Standard basis: LB

Eigenfunctions of the Laplace-Beltrami operator: $\Delta\phi_i = \lambda_i\phi_i$ [VLo8]

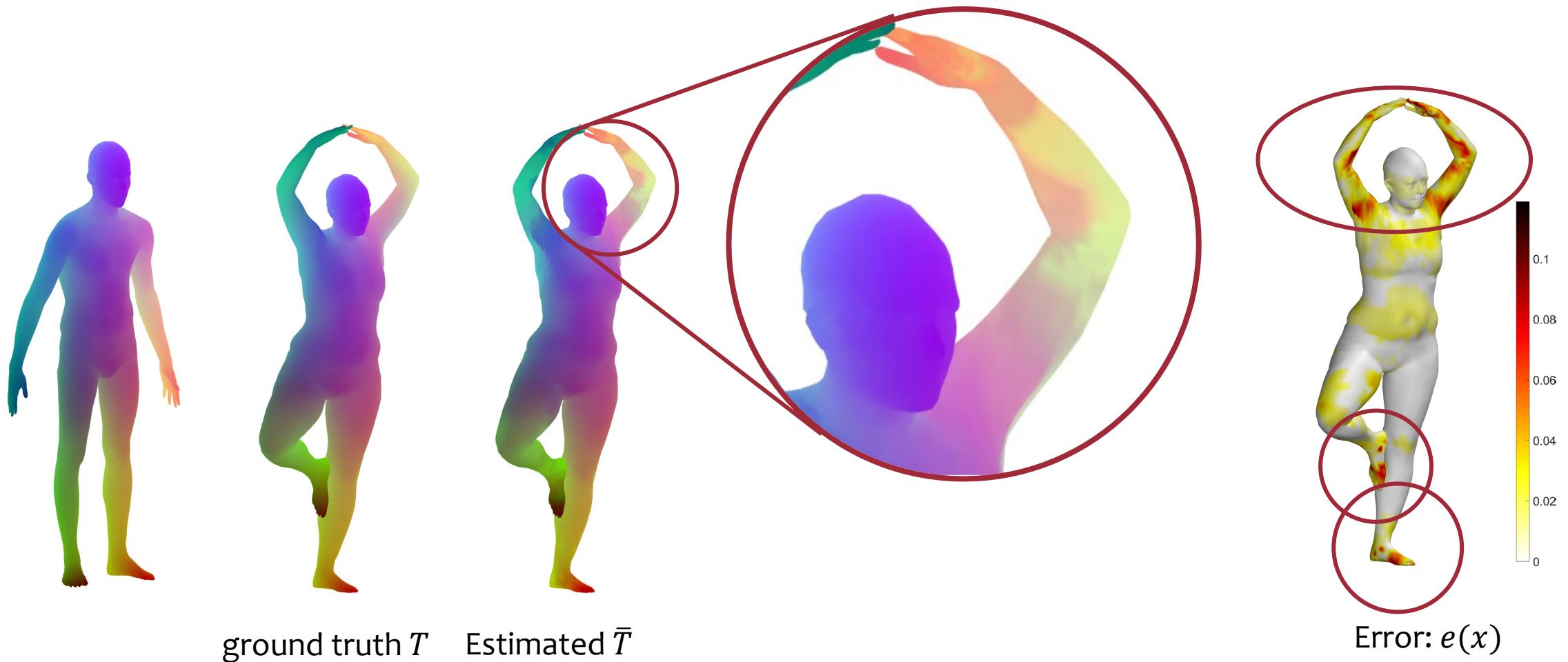
$$\Phi_{LB} = \left\{ \phi_1, \phi_2, \phi_3, \phi_4, \phi_5, \phi_6, \phi_7, \phi_8, \dots \right\}$$


- Orthonormal \Rightarrow efficient projection
- Ordered in frequency \Rightarrow low-pass filter approximation of functions
- Optimal k -dimensional basis for approximating smooth functions on a mesh [ABK15]



$$\tilde{f} = \Phi_{LB}\Phi_{LB}^T A_{\mathcal{M}} f$$

Errors in point-wise maps



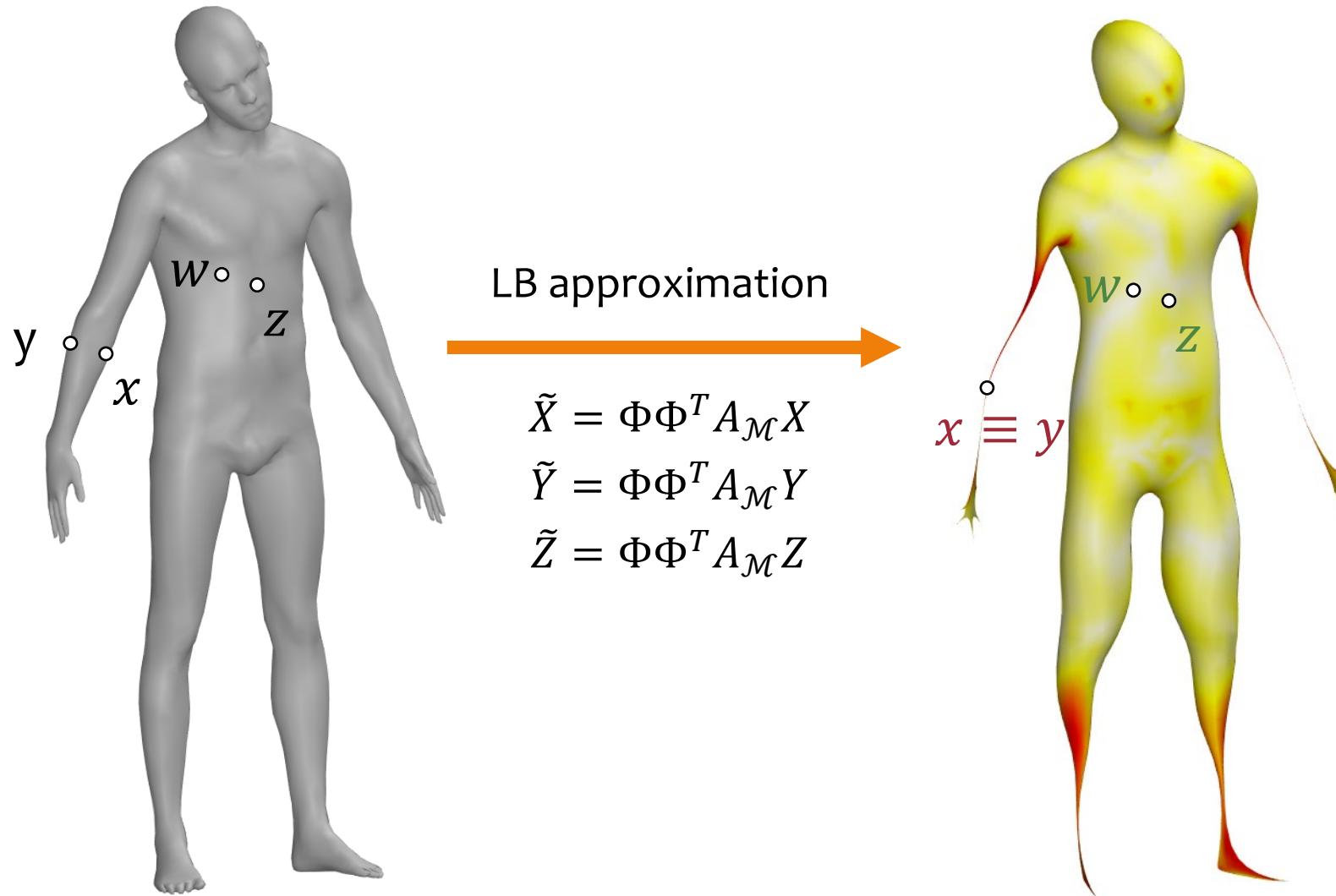
Limits of LB

The energy of LB is **not distributed evenly** on the mesh surface

- Low quality of representation provided by the embedding space in certain areas:
 - Discrimination power between different vertices
 - Locality preservation

We will
define
metrics

Energy distribution: intuition

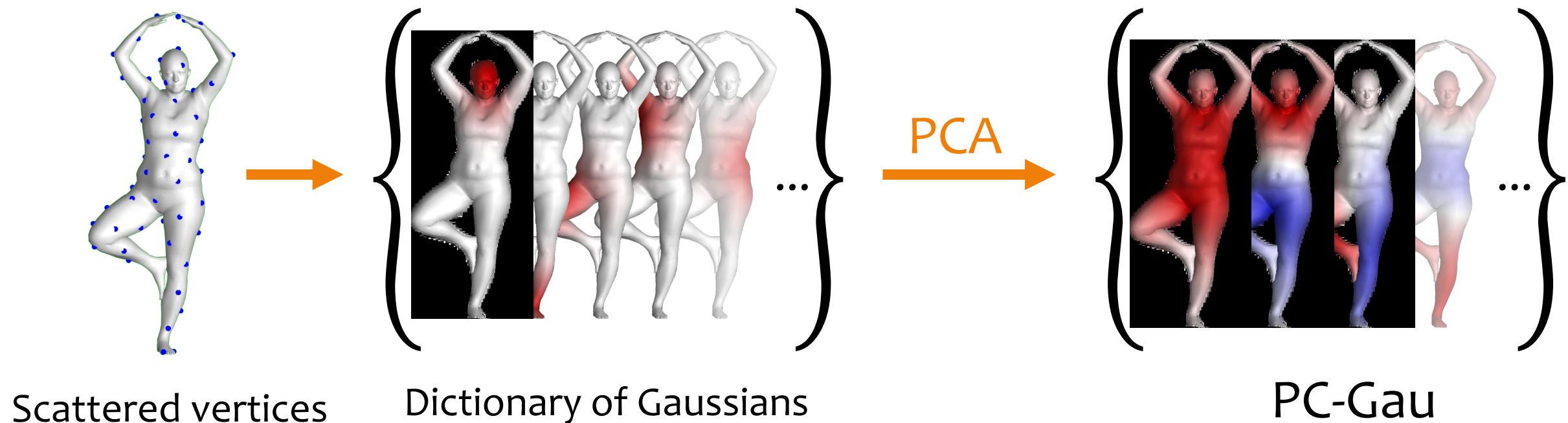


Our proposal: PC-GAU

- Basis for $\mathcal{F}(\mathcal{M}, \mathbb{R})$
- Designed to be used as a truncated basis in **functional maps** pipelines for shape matching
- Its energy is **evenly distributed** on the mesh surface

PC-GAU: construction

- Principal Components of a dictionary of Gaussian functions scattered on the mesh

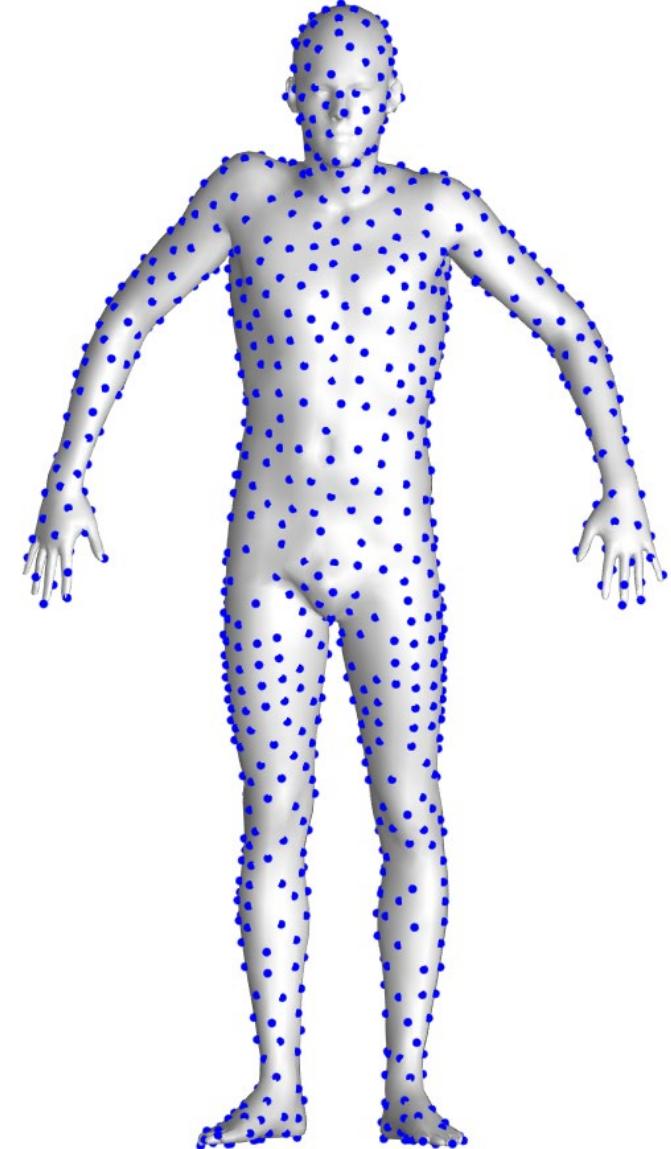


Subset of vertices Q

- Subset of q vertices $Q \subset V_{\mathcal{M}}$
- Farthest Point Sampling (Euclidean distance)

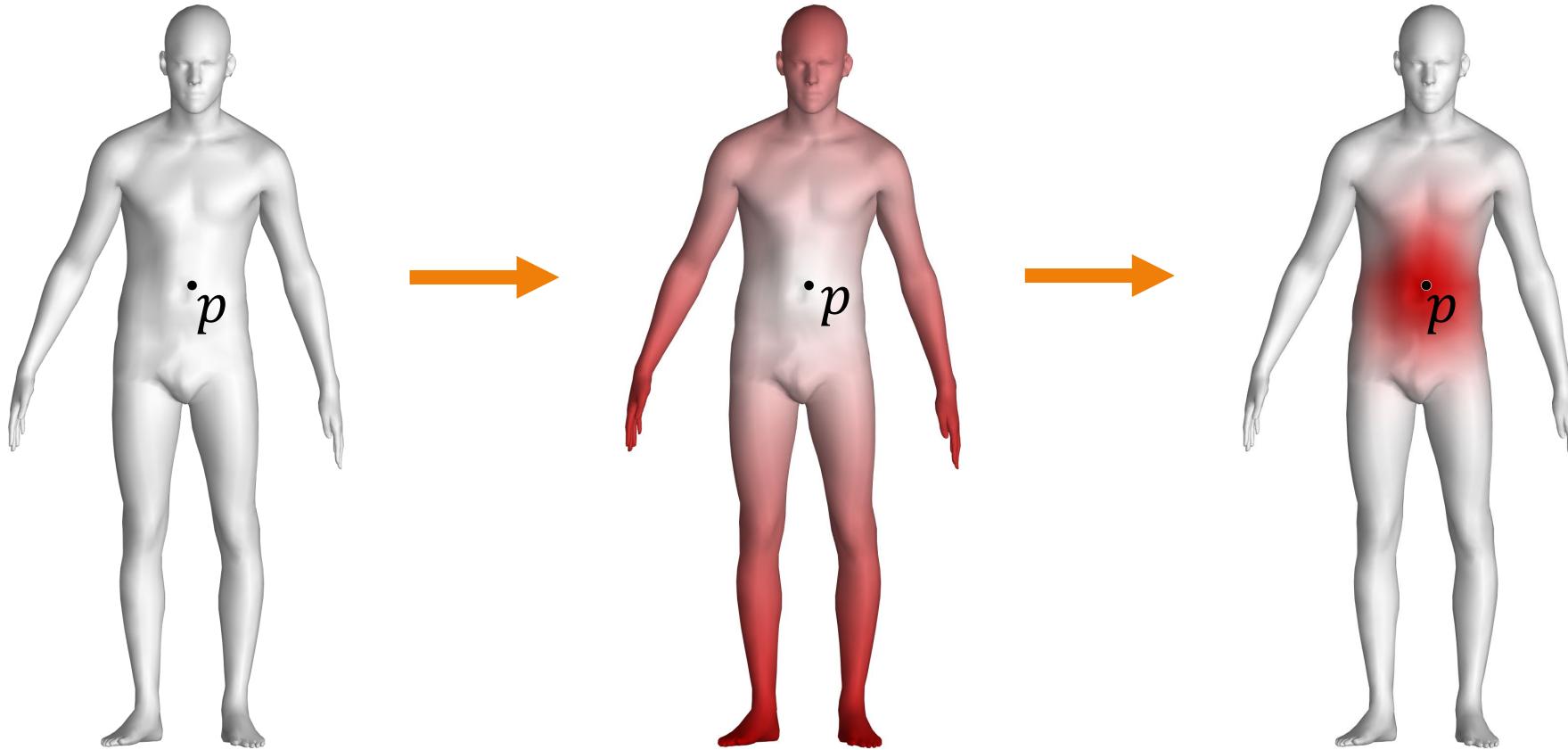


Evenly scattered on the surface



$$q = 1000$$

Gaussian function centered in $p \in Q$



$$D_p(x) = \text{geoDist}_{\mathcal{M}}(p, x) \\ x \in V_{\mathcal{M}}$$

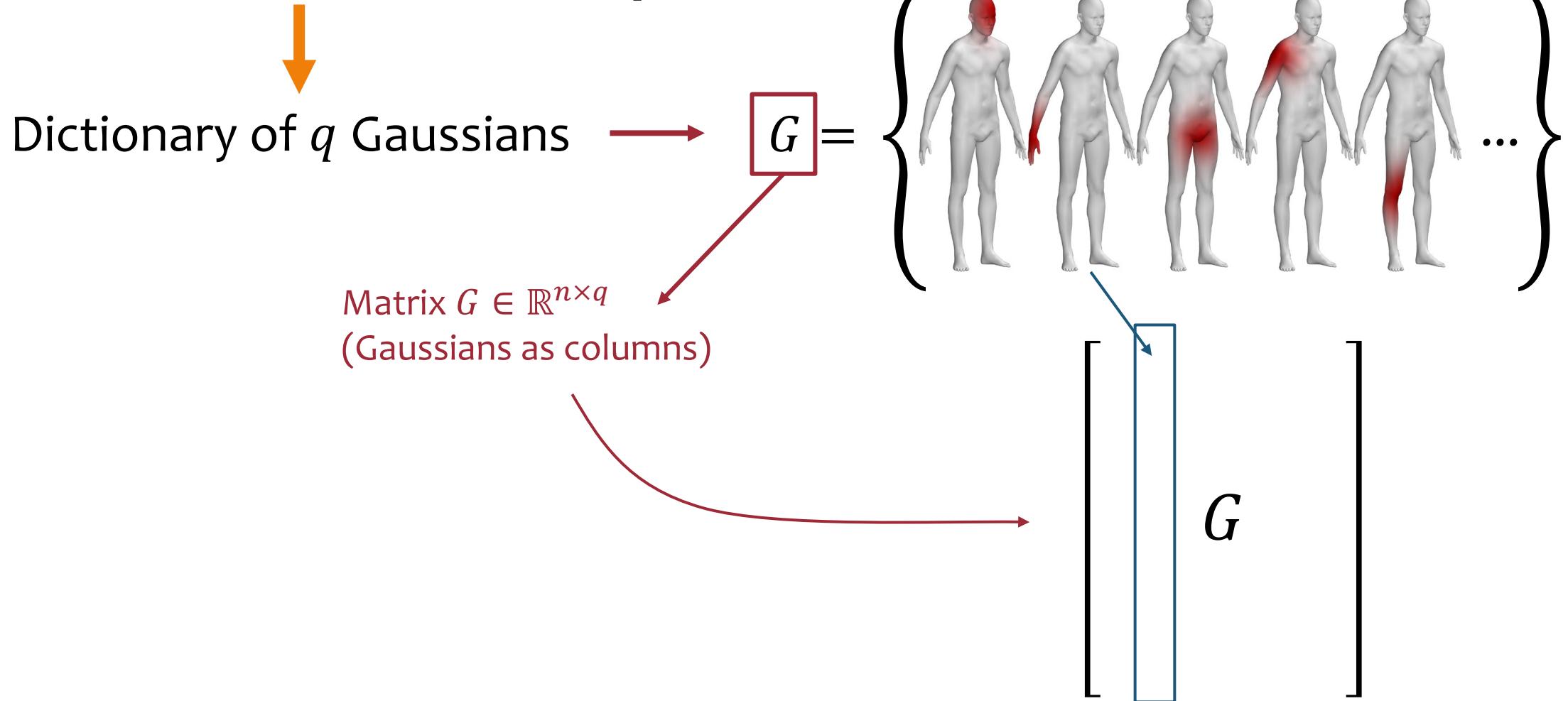
$$G_p(x) = \exp(D(x)^2 / \sigma) \\ x \in V_{\mathcal{M}}$$

Parameter σ :
Gaussian
amplitude

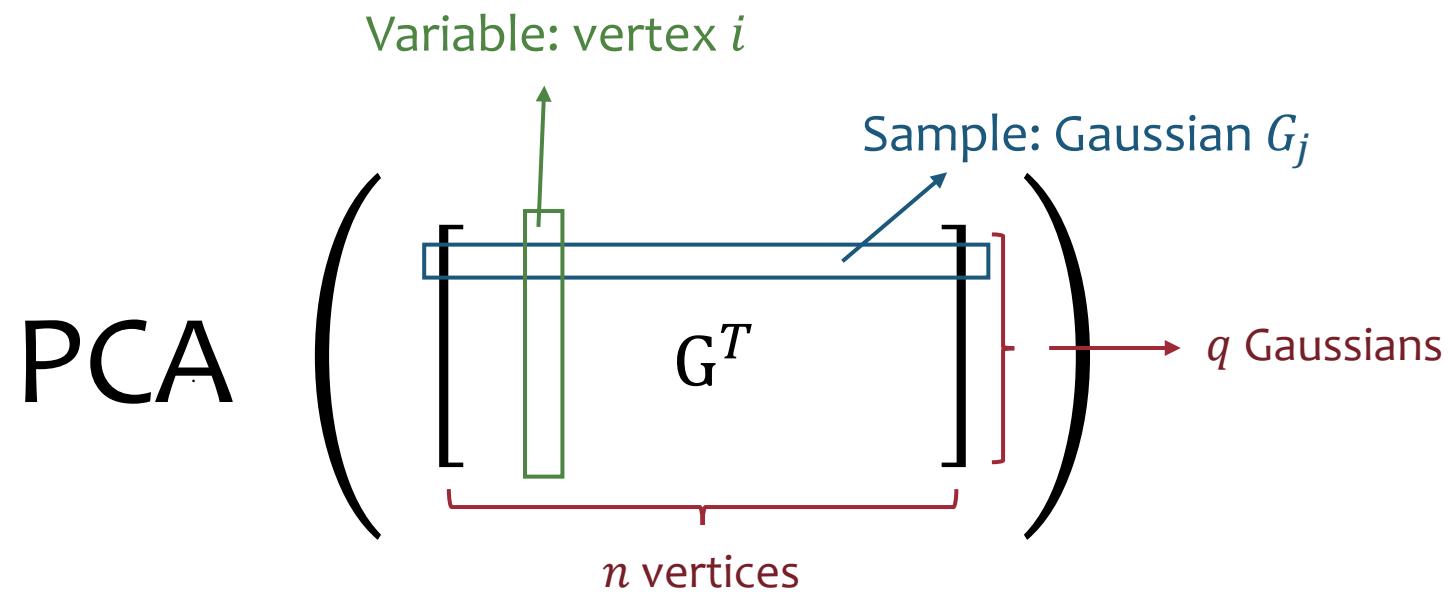


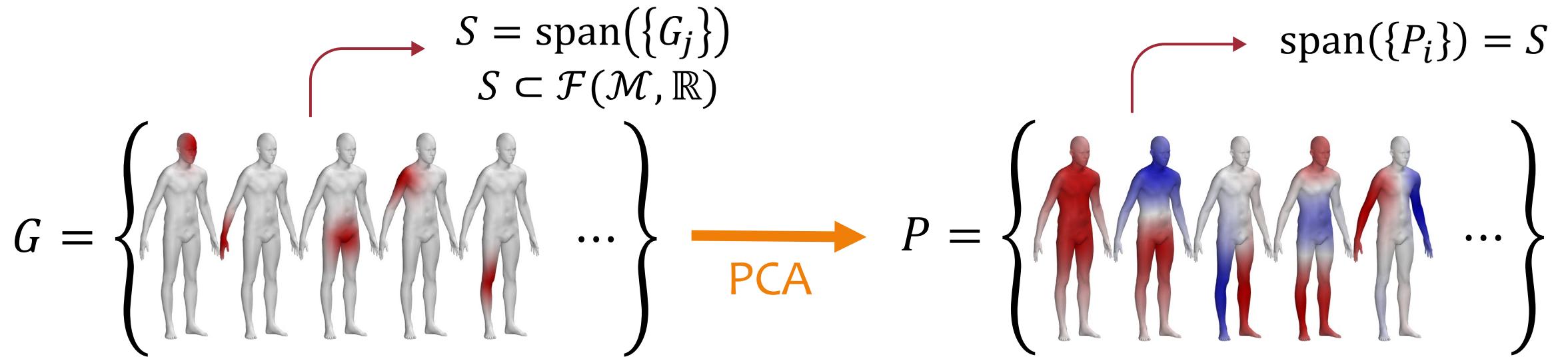
Dictionary of Gaussians

A Gaussian centered in each $p \in Q$



PCA computation

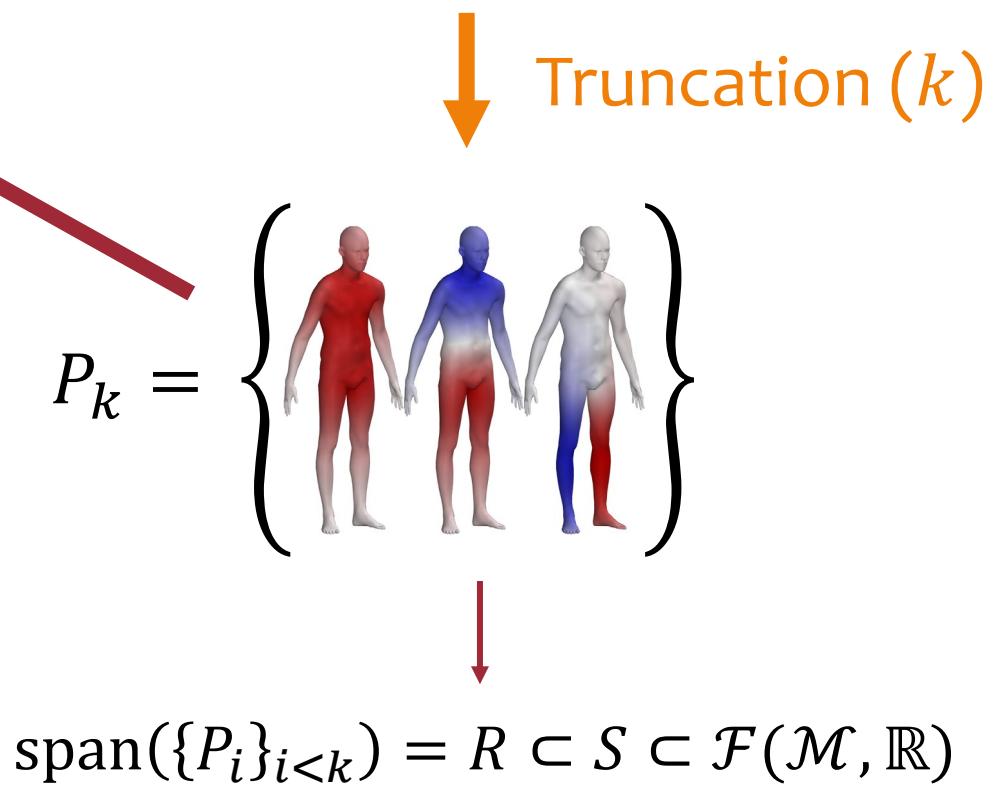




Reconstruction error on G_j

$$P_k = \arg \min_{P \in \mathbb{R}^{n \times k}} \left\{ \sum_j \overbrace{\|G_j - P_k P_k^T A_{\mathcal{M}} G_j\|}^{\text{Reconstruction error on } G_j} \right\}$$

s.t. $\underbrace{P_k^T A_{\mathcal{M}} P_k}_{\text{Orthonormality w.r.t inner product } \mathcal{M}} = I_k$



Even distribution of basis energy

Basis energy -> power of representation of
the embedding space

- Discrimination power \longrightarrow $\text{Dis}(x)$
- Locality preservation \longrightarrow $\text{EGDC}(x)$

Discrimination power

Assign sufficiently **distant embeddings** to different vertices

Function on \mathcal{M}

$$Dis(x) = \frac{\|Emb(x) - Emb(y)\|_2}{geoDist(x, y)}$$

Nearest neighbor
in embedding space

$$y = \arg \min_{z \in V_{\mathcal{M}} \setminus \{x\}} \{\|Emb(z) - Emb(x)\|_2\}$$

Locality preservation

Correlation to measure the order preservation
between embedding and geodesic distances

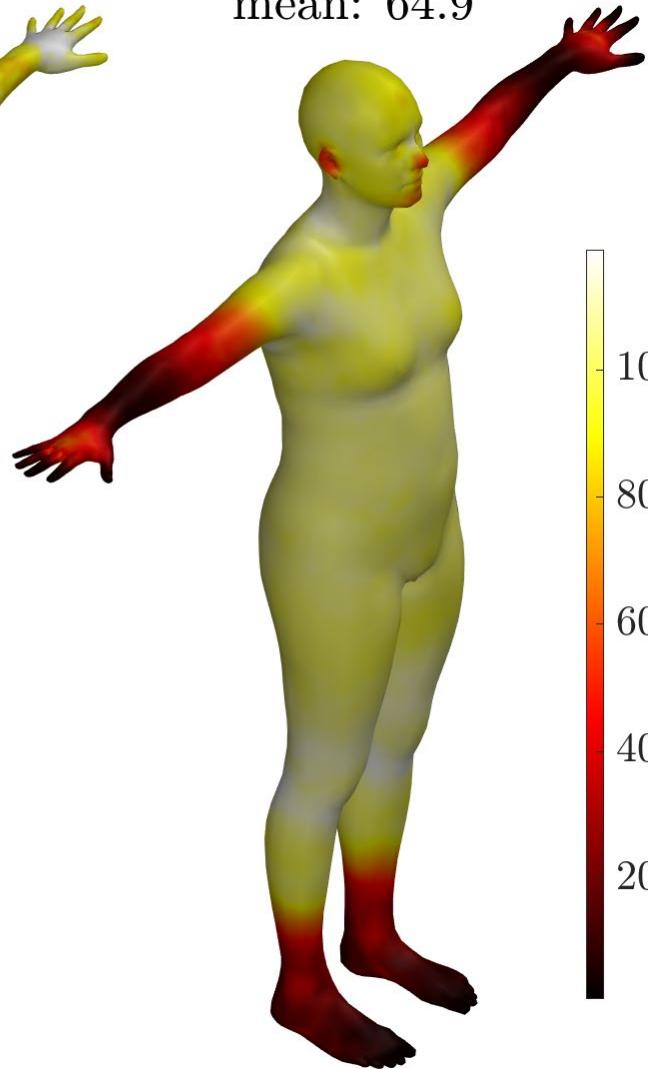
$$EGDC(x) = \text{corr} (\text{geoDist}_{\mathcal{M}}(x, y), \| \text{Emb}(x) - \text{Emb}(y) \|_2)_{y \in E}$$

E set of s embeddings closest to $\text{Emb}(x)$

ours
mean: 102.3



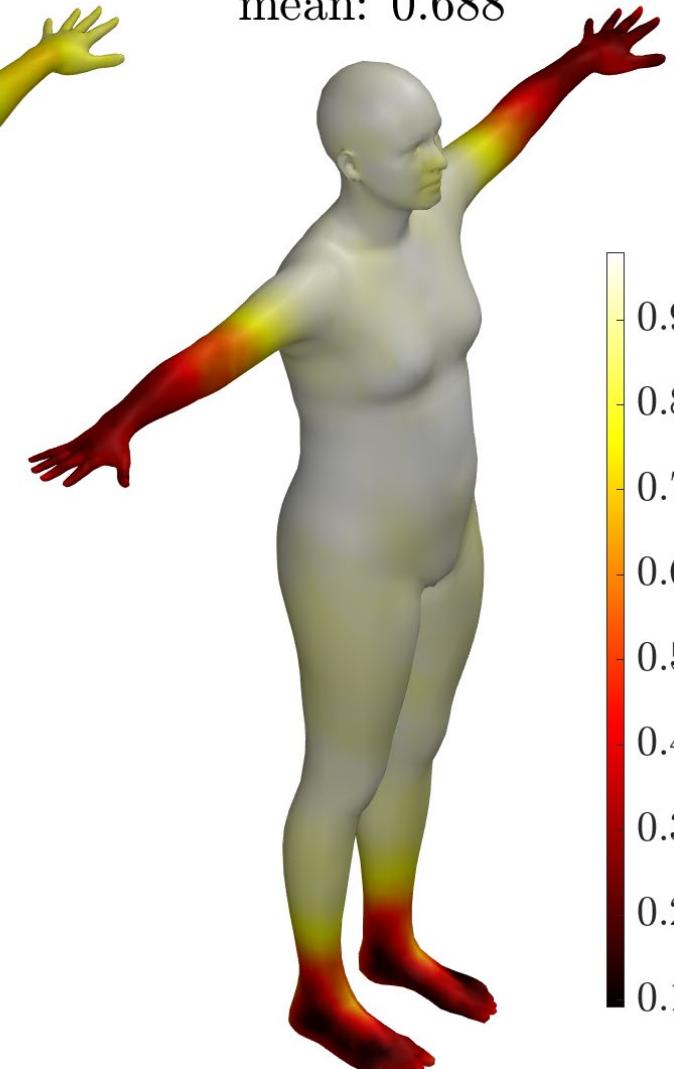
LB
mean: 64.9



ours
mean: 0.819



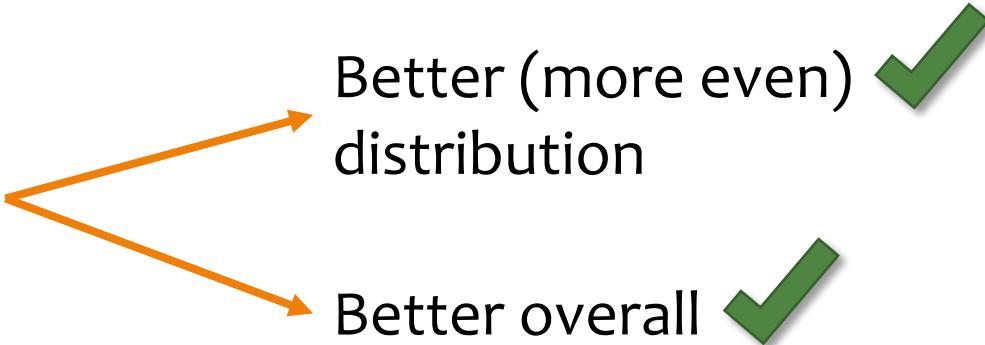
LB
mean: 0.688



Discrimination power $Dis(x)$

Locality preservation $EGDC(x)$

Expressive power
of the basis



Better accuracy in point-wise maps



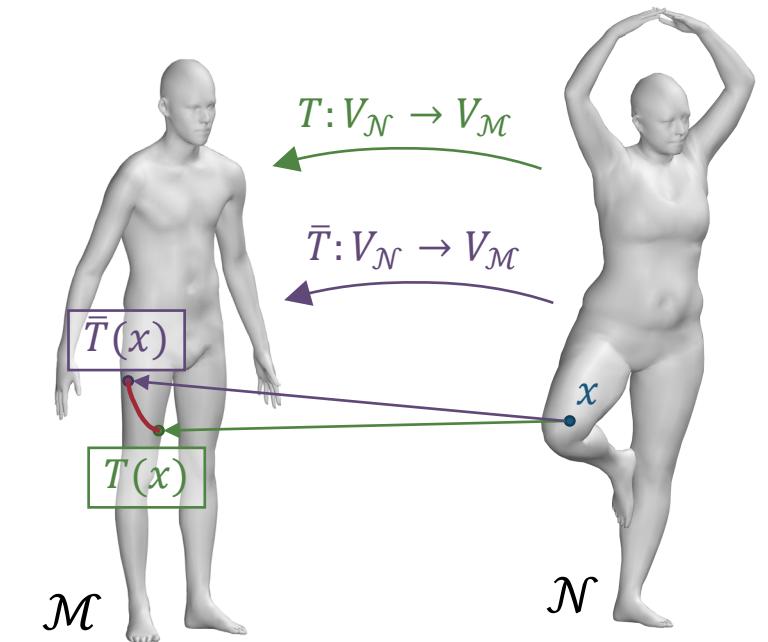
Experimental Evaluation

- Randomly select pairs of meshes from established datasets
- Insert LB and PC-GAU in the same shape matching pipeline
- Compare the accuracy of the point-wise maps obtained

Point-wise accuracy

- Evaluate $\bar{T}: V_{\mathcal{N}} \rightarrow V_{\mathcal{M}}$ wrt $T: V_{\mathcal{N}} \rightarrow V_{\mathcal{M}}$ (given)
- Geodesic error:

$$e(x) = \text{geoDist}_{\mathcal{M}}(T(x), \bar{T}(x))$$



Average Geodesic
Error (AGE)

Overall accuracy

Cumulative error curves

% Correspondences
Within error threshold

Plot on mesh

Spatial distribution

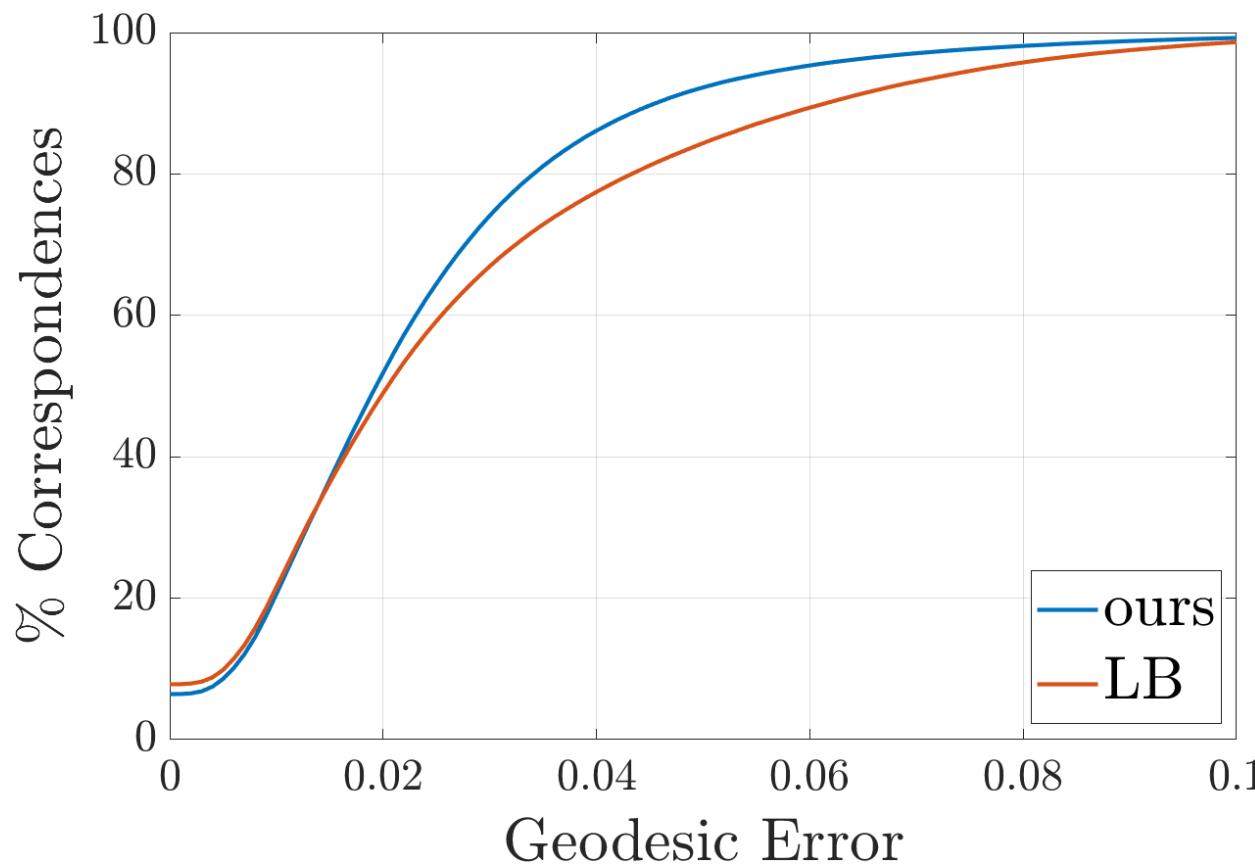
C computed from the ground-truth correspondence

- Test setting only
- Best possible C ,
given Φ and Ψ

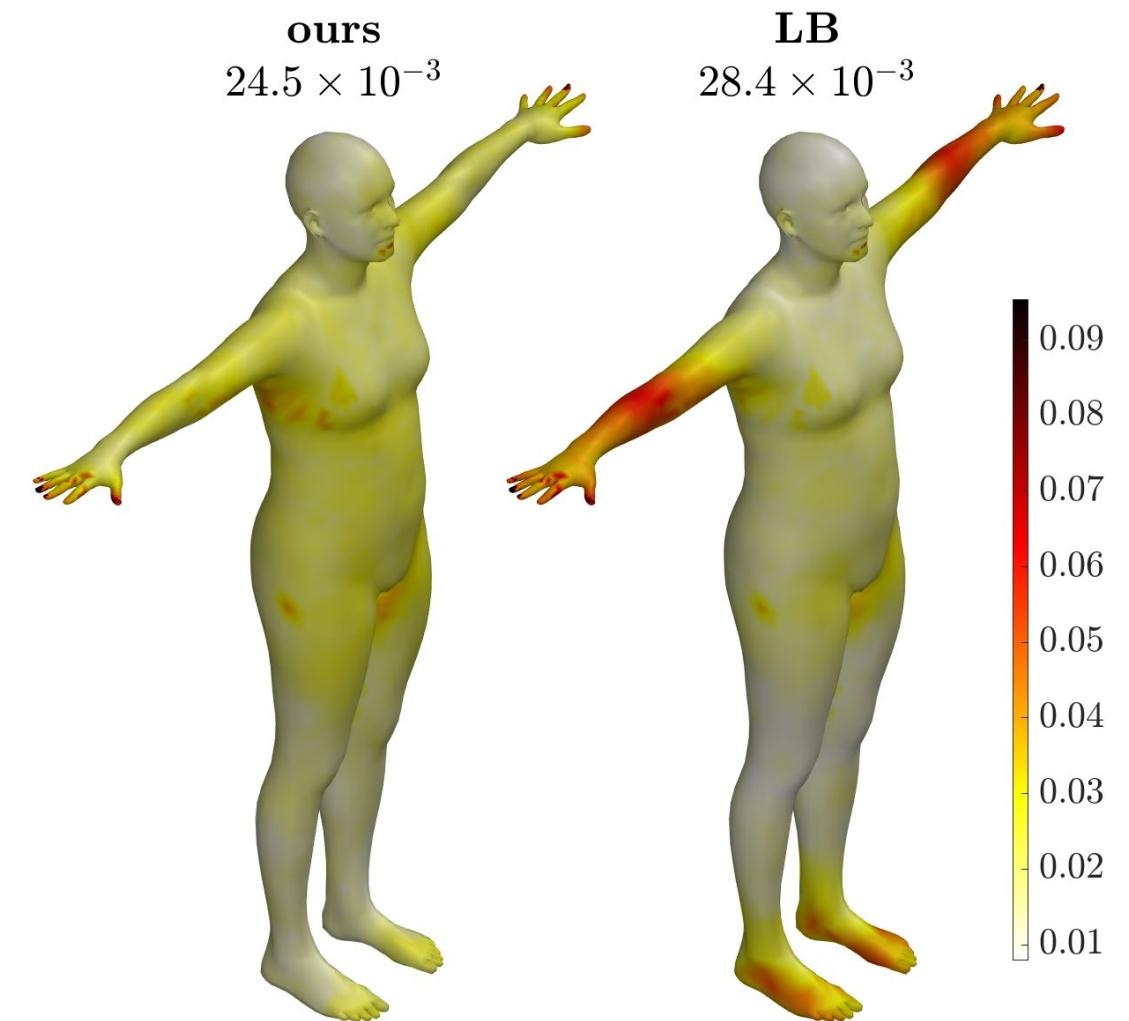
Average Geodesic Error

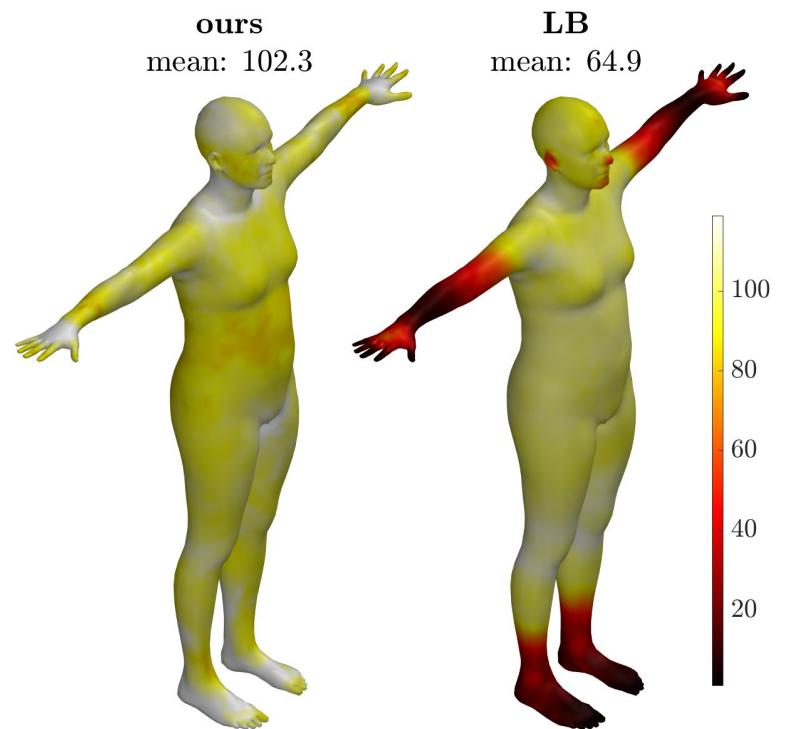
Dataset	Ours ($\times 10^{-3}$)	LB ($\times 10^{-3}$)
FAUST	15,7	19,7
MWG	20,8	24,9
MWG iso	13,6	17,3
TOSCA	7,7	12,3
SHREC19	24,5	28,4

SHREC19 dataset

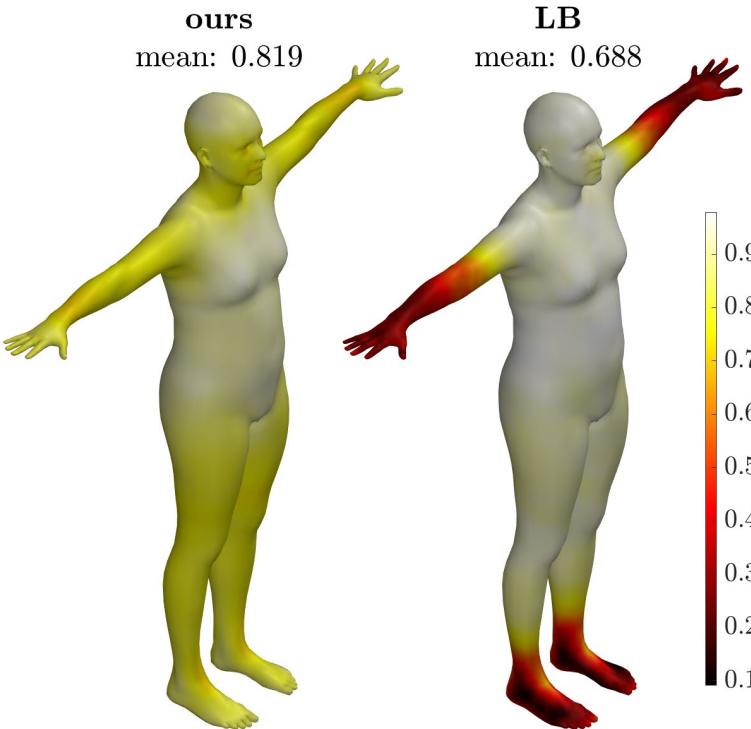


AGE: Ours: $24,5 - LB: 28,4$

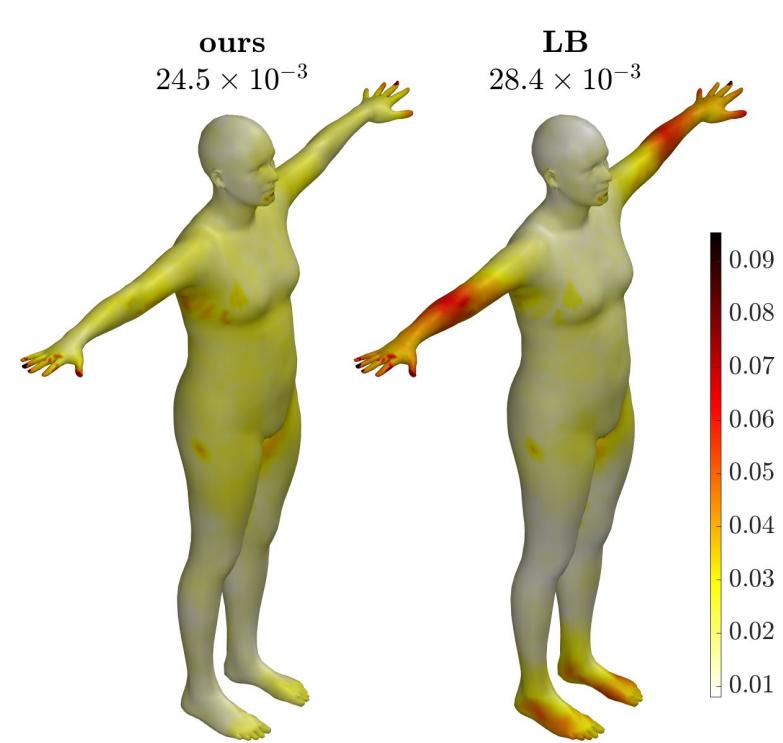




Discrimination power $Dis(x)$



Locality preservation $EGDC(x)$



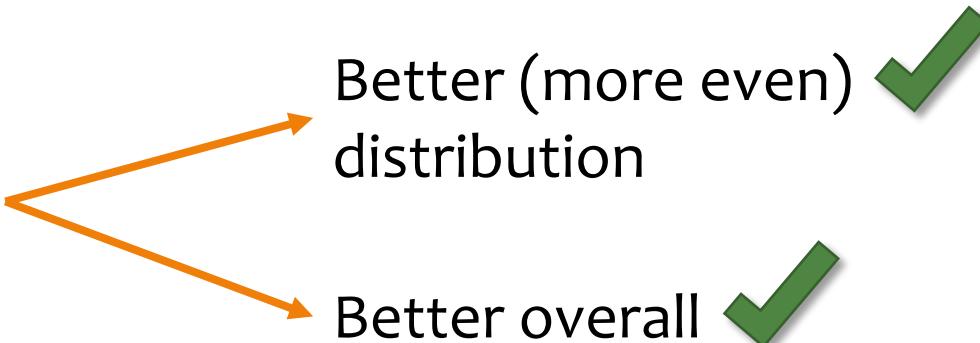
Geodesic Error $e(x)$

C estimated in real settings

Dataset	Average Geodesic Error			
	Ours ($\times 10^{-3}$)	LB ($\times 10^{-3}$)	Ours ($\times 10^{-3}$)	LB ($\times 10^{-3}$)
FAUST	28,0	30,6	24,0	26,1
MWG	58,7	58,7	51,2	70,6
MWG iso	25,9	27,6	18,6	27,2
TOSCA	12,7	19,8	9,7	20,5
SHREC19	56,2	78,5	34,5	39,4

C estimated with product preservation [NO17] C estimated with ZoomOut [MRR*19]

Expressive power
of the basis



Better accuracy in point-wise maps ✓

References

- [ABK15] Y. AFLALO, H. BREZIS, AND R. KIMMEL. On the optimality of shape and data representation in the spectral domain. *SIAM J. Imaging Sciences*.
- [MRR*19] S. MELZI, J. REN, E. RODOLÀ, A. SHARMA, P. WONKA, AND M. OVSJANIKOV. ZoomOut: Spectral upsampling for efficient shape correspondence. *ACM Transactions on Graphics*.
- [NO17] D. NOGNENG AND M. OVSJANIKOV. Informative descriptor preservation via commutativity for shape matching. *Computer Graphics Forum*.
- [OBCS*12] M. OVSJANIKOV, M. BEN-CHEN, J. SOLOMON, A. BUTSCHER, AND L. GUIBAS. Functional maps: a flexible representation of maps between shapes. *ACM Transactions on Graphics*.
- [VL08] B. VALLET AND B. LÉVY. Spectral geometry processing with manifold harmonics. *Computer Graphics Forum*.